

Metrology for accurate satellite-based observations of climate variables

15 November 2022

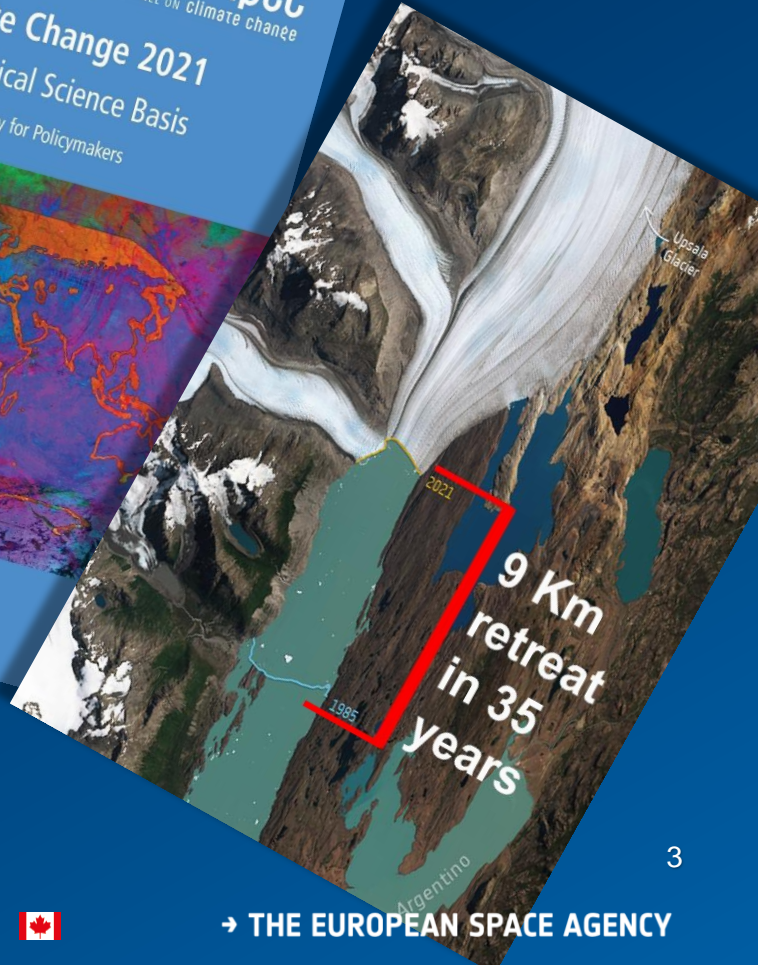
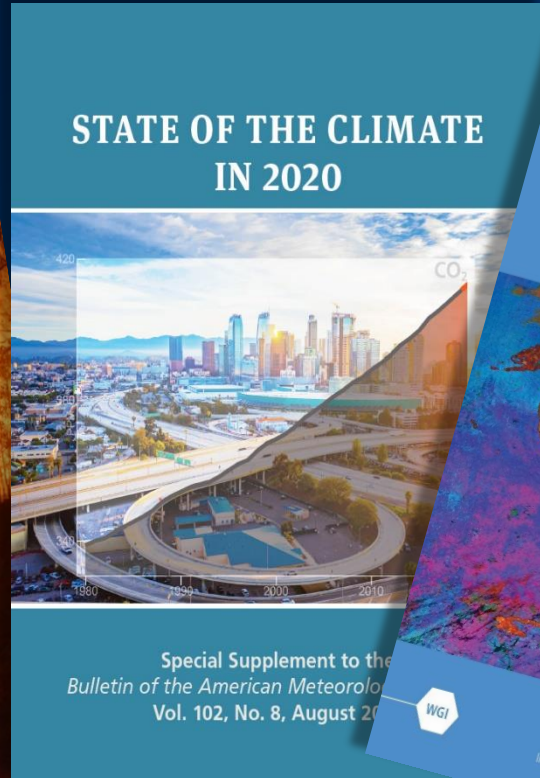
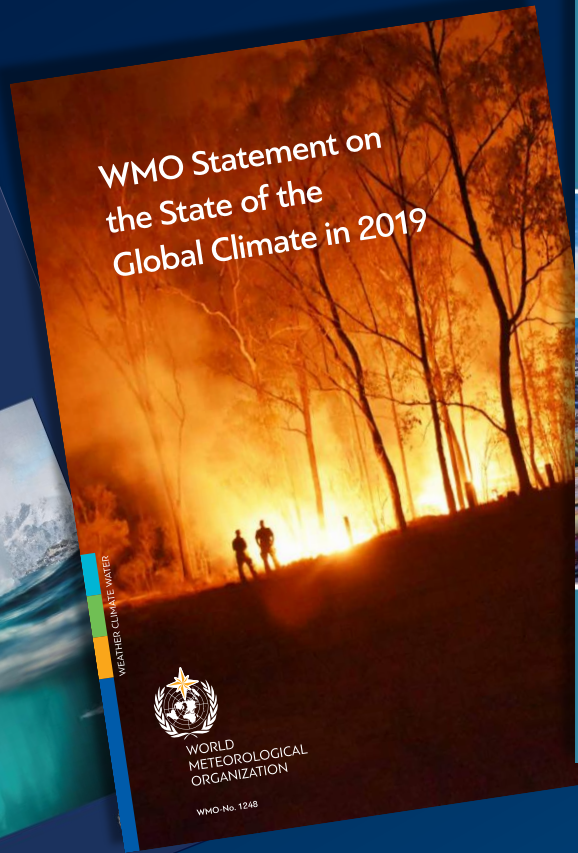
Dr. Craig Donlon

Head of Earth Surfaces & Interior Section,
Earth & Mission Sciences Division, ESTEC, ESA

**27th meeting
of the General Conference
on Weights and Measures**



EO provides unequivocal evidence and facts in climate reports





Copernicus is the largest producer of EO data in the world

All global
landmass is
observed every
5 days at 10m
resolution

**25 TB of Daily Data
Production by Sentinels**

**250 TB of Daily Sentinel Products
Disseminated for Services to Society**

Examples of Evolving needs in Metrology for Environment and Climate at the European Space Agency.

Why is a Climate Observing System Important?

- Climate change has very different requirements than weather observations:
 - 10 times more accuracy: 0.03K instead of 0.3K
 - 10 times as many key variables: 50 vs 5
 - Prediction time scales of decades vs days
 - Need for independent observations and analysis to verify surprises: cannot go back in time to verify them
 - Observations that must maintain consistency over many decades
 - Much longer than space based instrument lifetimes (5-15 years)
 - Longer than a scientist's career
- Climate system physical, chemical, and biological processes occur on scales that vary from millennia down to seconds, and from global down to micrometers
- The challenge of such an observing system exceeds anything humanity has attempted to date for any scientific field.

7

(Bruce Wielicki)

CEOS

GSICS

SI-Traceable Space-based Climate Observing System:
a CEOS and GSICS Workshop
National Physical Laboratory,
London, UK,
9-11 Sept. 2019

SITSCOS Workshop Report



Editors: Nigel Fox, Tim Hewison, Greg Kopp, Bruce Wielicki

<https://doi.org/10.47120/npl.9319>

TAKING THE PULSE OF THE PLANET

Essential Climate Variables are key indicators that describe Earth's changing climate. Scientists use these variables to study climate drivers, interactions and feedbacks, as well as reservoirs, tipping points, and fluxes of energy, water and carbon.

The climate-quality datasets produced by the Climate Change Initiative are a major contribution to the evidence base used to understand climate change.

“ Satellite products provide a valuable complement to in-situ measurements. These observations are valuable (high confidence) for regional applications since they provide multi-channel images at very high spatiotemporal resolutions ”

IPCC AR6 2021



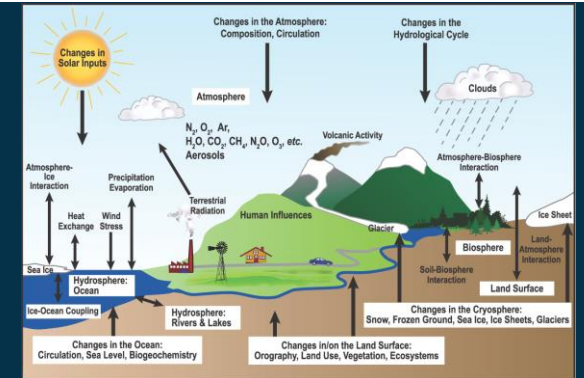
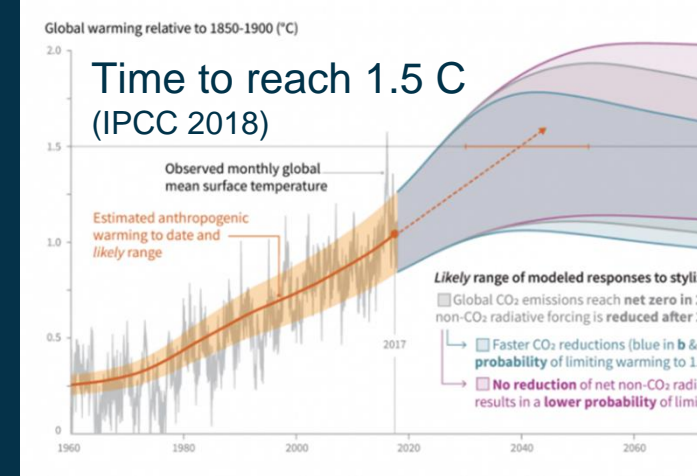
The critical role of metrology and SI in addressing global Climate challenges

NEED:- Trustworthy observations from space to:

- Monitor and assess progress resulting from mitigation
- Improve understanding of climate sensitivities, dependencies & forecasts
- Support adaptation, Food security emergency response, de-risk investments

REQUIRES

- Quantitative, comprehensive, accessible, useable data
- Integrated, interoperable global observing system (space and in-situ)
- Robust reference(s) (benchmarks) against which to reliably measure change in as short a timescale as possible
- International acceptance



Confidence from metrological traceability to international standards (SI) at location of measurement

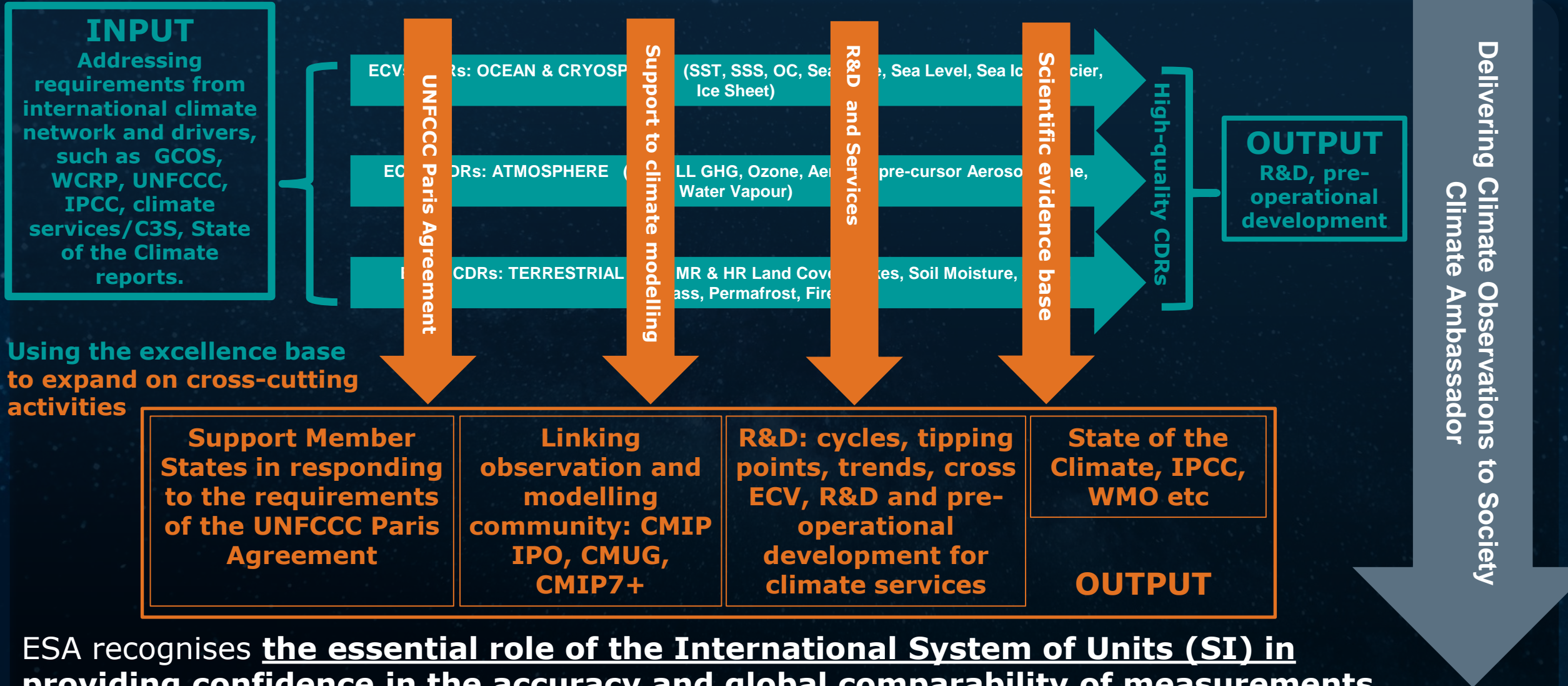


When & how big do we build the next Thames barrier?

Climate-Space – ESA's role...

International Climate Network

UNFCCC | IPCC | GCOS | WCRP | Future Earth | CEOS | CGMS | GEO | EUMETSAT | ECMWF | C3S | SCO | CMIP ...



ESA recognises the essential role of the International System of Units (SI) in providing confidence in the accuracy and global comparability of measurements needed for protection of the environment, global climate studies and scientific research



Core principles of metrology



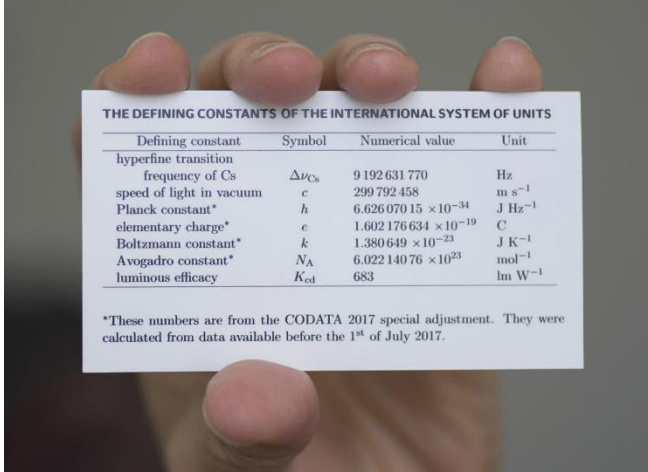
STABILITY
Century scale

INTEROPERABILITY
equivalence world wide

COHERENCE
Combining different measurements



20 May 1875



20 May 2019

TRACEABILITY

UNCERTAINTY

COMPARISON



Steps to an FDR / TDP or FRM Uncertainty budget




**MEASURAND
01**

Define the
measurand
and
measurement
function




**TRACEABILITY
02**

Establish the
traceability
with a
diagram



**UNCERTAINTY
03**

Evaluate each
source of
uncertainty
and fill out an
effects table



**CALCULATE
04**

Calculate the
product and
its
uncertainty



**STORE
05**

Store
relevant
information
for future
users

Guidance documentation and training
materials available at www.qa4eo.org

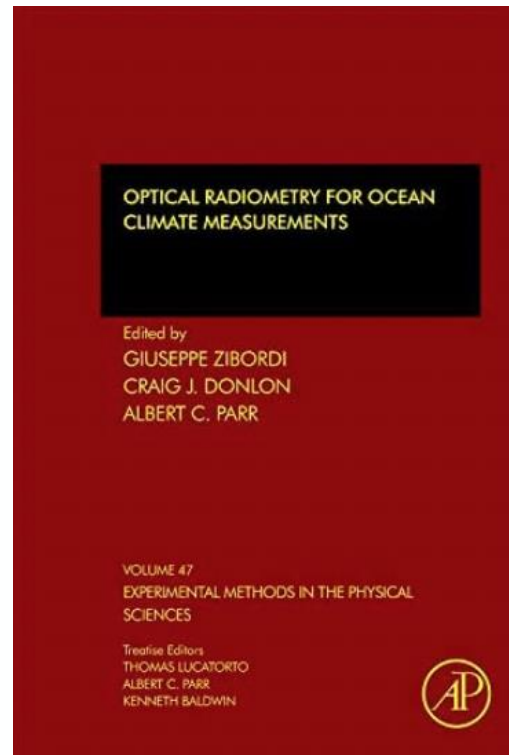
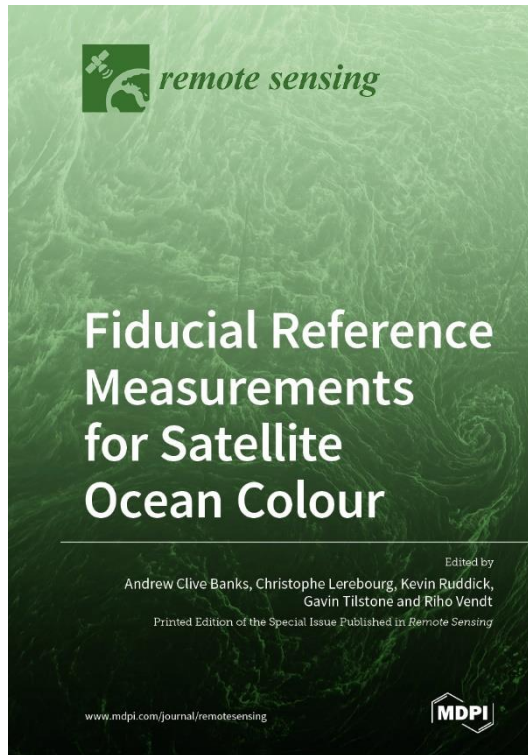
Fiducial Reference Measurements (FRM)



Fiducial Reference Measurements (FRM) are a suite of **independent, fully characterized, and traceable ground measurements** that follow the guidelines outlined by the GEO/CEOS Quality Assurance framework for Earth Observation ([QA4EO](#)).



<https://ships4sst.org/> <https://frm4soc.org/> <http://www.frm4sts.org/> <https://www.frm4alt.eu> <https://frm4veg.org/>



FRM-BOUSSOLE: Buoy for the acquisition of long-term optical time series

<http://www.obs-vlfr.fr/Boussole>

Pandonia FRM: Fiducial Reference Measurements for Ground-Based Direct-Sun Air-Qu

<https://www.pandonia-global-network.org/>

Fiducial Reference Measurements for Ground-Based DOAS Air-Quality Observations

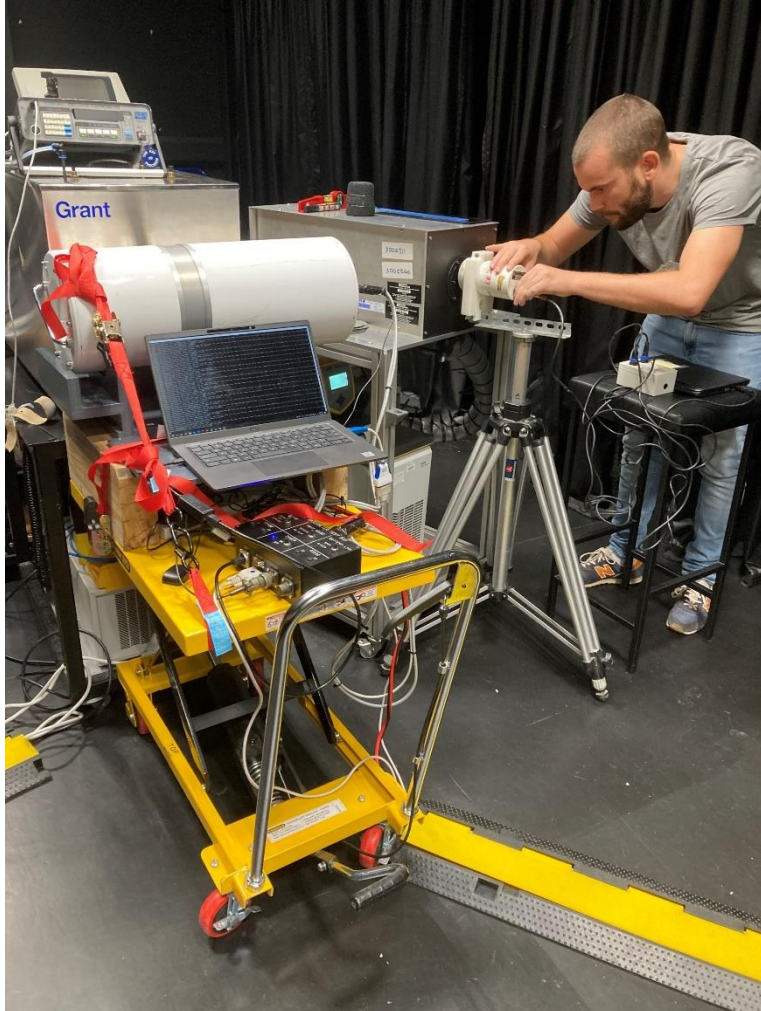


<https://frm4doas.aeronomie.be/>



Lab comparison

13th -17th June, 2022, @ NPL, Teddington, UK



Radiometer comparison

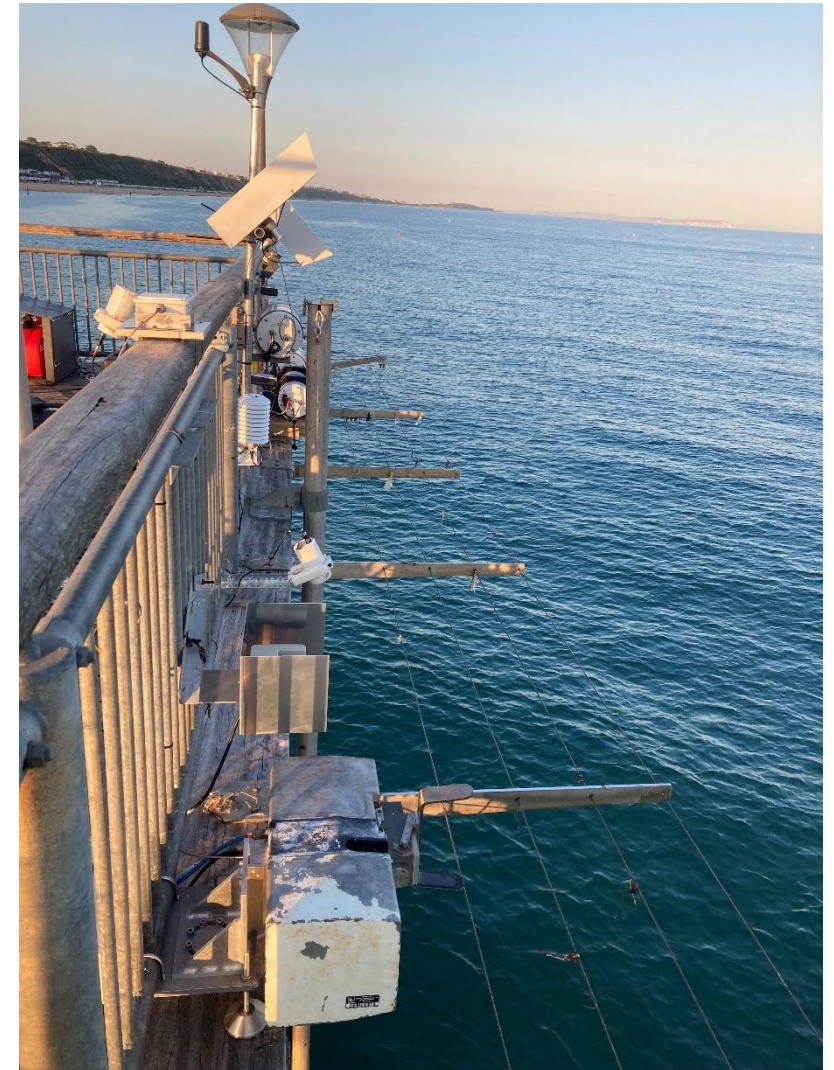


Blackbody comparison

Field comparison



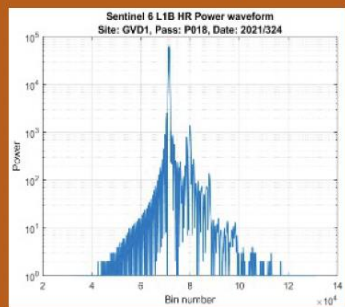
Preparation



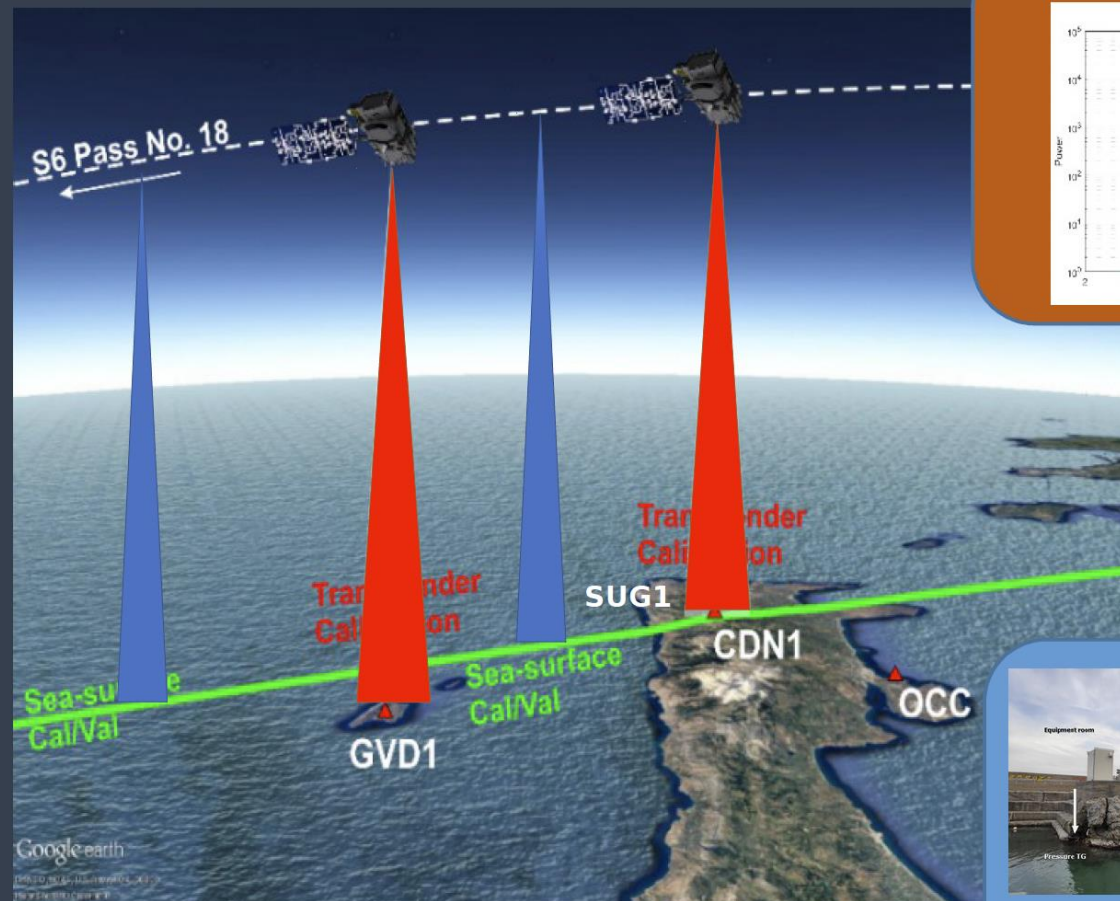
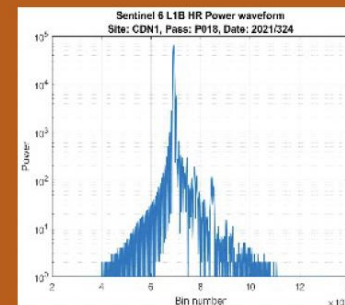
After set-up

Simultaneous Transponder & Sea-Surface Cal/Val

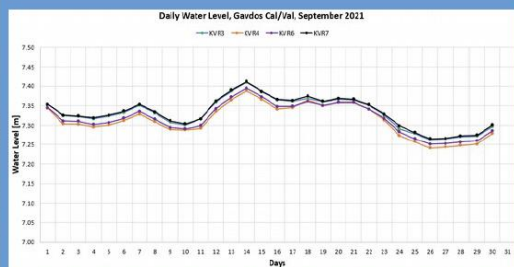
GVD1 Transponder



CDN1 Transponder



Gavdos sea-surface



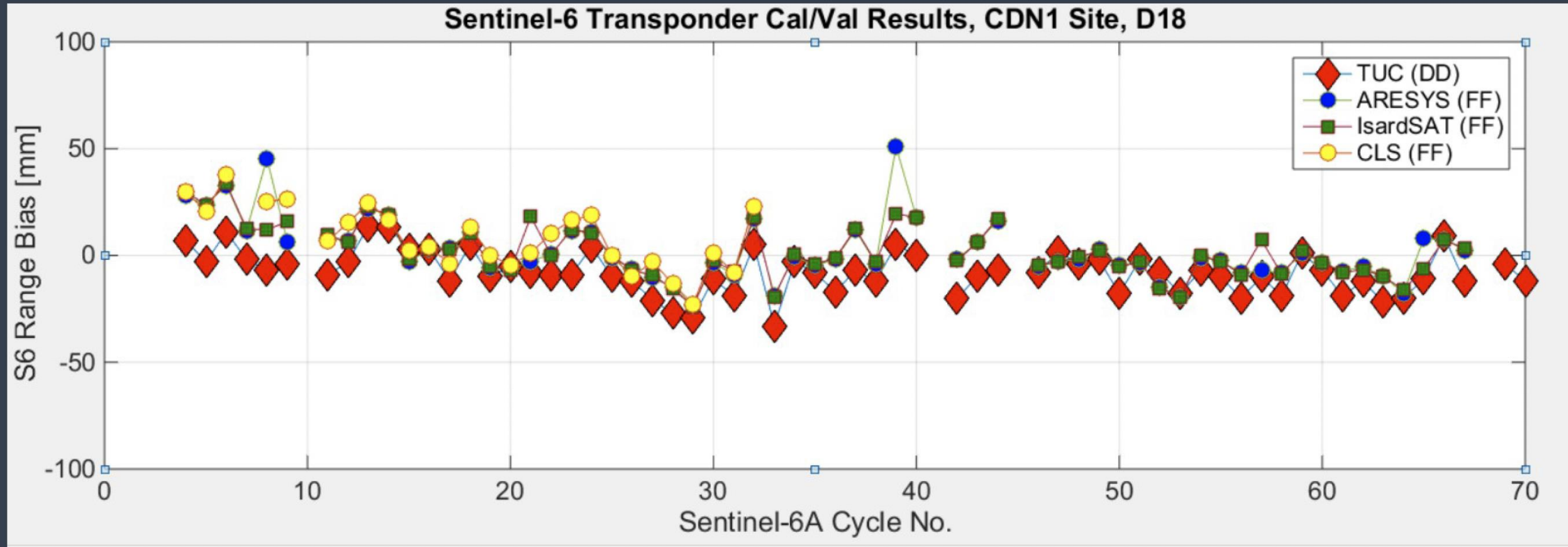
RDK1



SUG1 sea-surface



TPX- Range Bias @ CDN1 Transponder



Uncertainty and SI traceability in Satellite Mission Requirements

ESA UNCLASSIFIED – For ESA Official Use Only

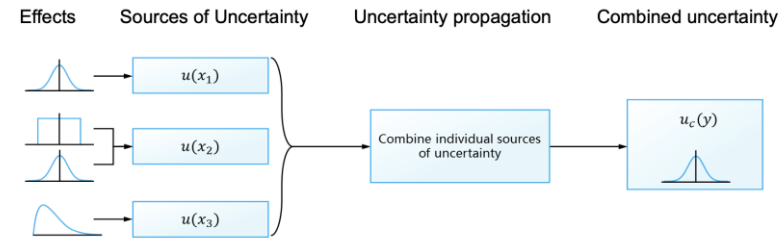
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Copernicus Imaging Microwave Radiometer (CIMR) Mission Requirements Document

Prepared by Earth and Mission Science Division
Reference ESA-EOPSM-CIMR-MRD-3236
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Status DRAFT for review
Document type Mission Requirements Document (MRD)
Distribution ESA Unclassified – For Official Use

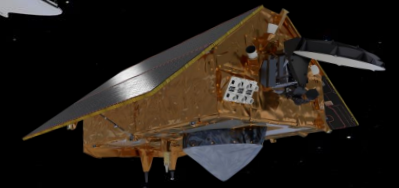
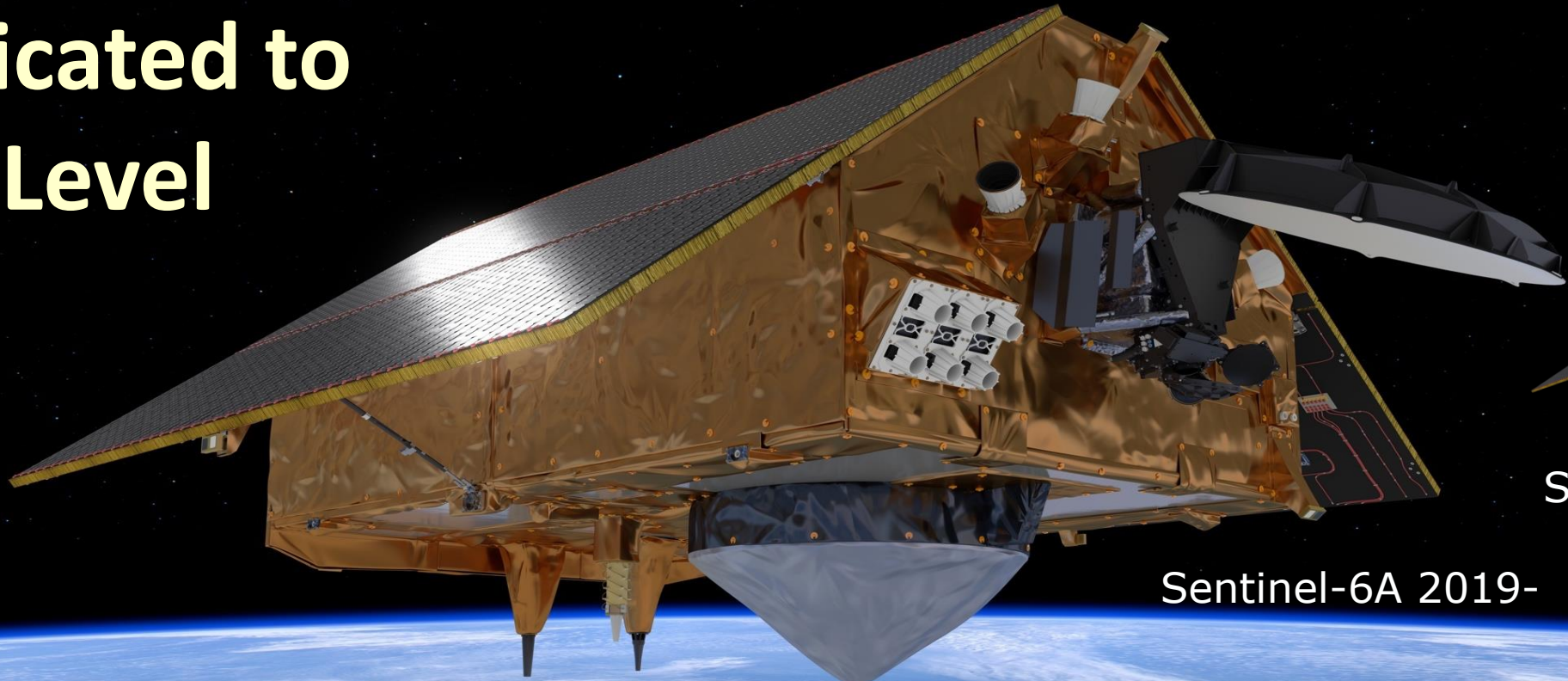
$$u_{total}^2 \cong u_{NE\Delta T}^2 + u_{orbit-stability}^2 + u_{lifetime-stability}^2 + u_{pl-cal}^2 + 0$$

No more ARA! Follow the BIPM GUM approach



- MRD-500 The calibration of L1b brightness temperature in all channels shall be maintained during science measurement acquisition using an on-board calibration system with at least two reference values that are traceable to SI.
- MRD-770 A CIMR L1b data product shall contain the information necessary to generate all L2 products and populate the CIMR L1b uncertainty model.
- MRD-780 Standard total uncertainties and quality indicators shall be delivered for all CIMR measurements in a L1b data product.

Sentinel-6 - dedicated to Sea Level Rise

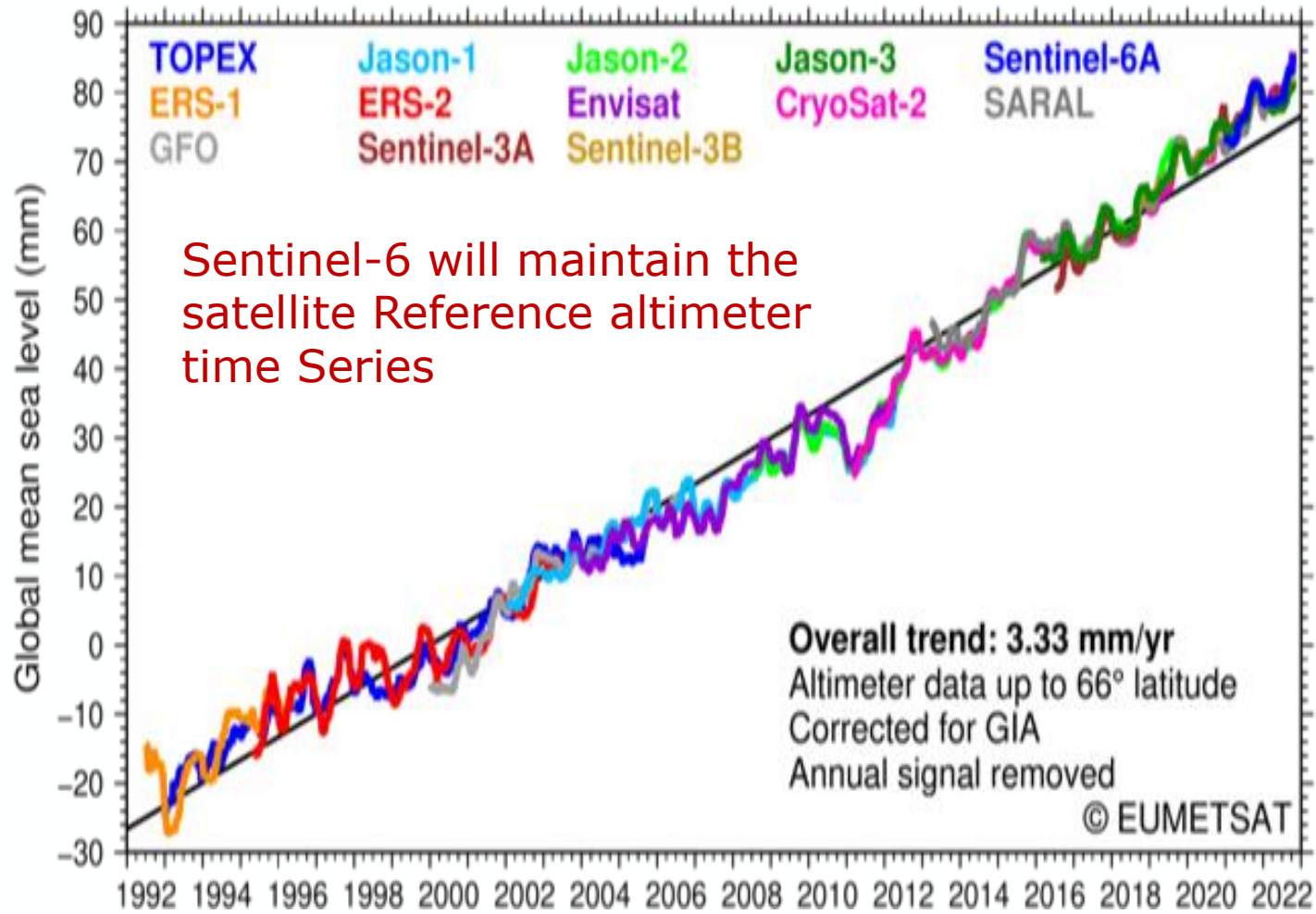


Sentinel-6B 2025-

Sentinel-6A 2019-



Sea-Level rise is a societal threat

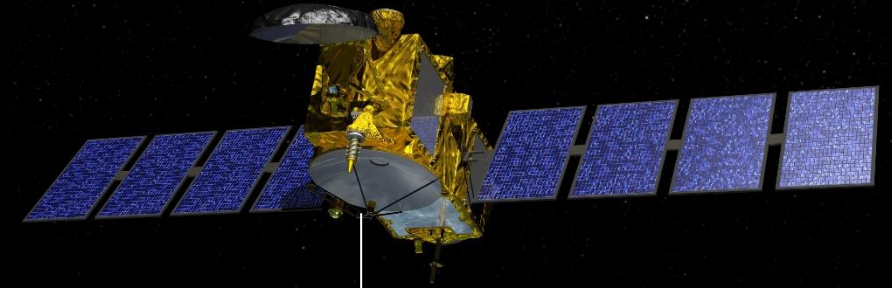
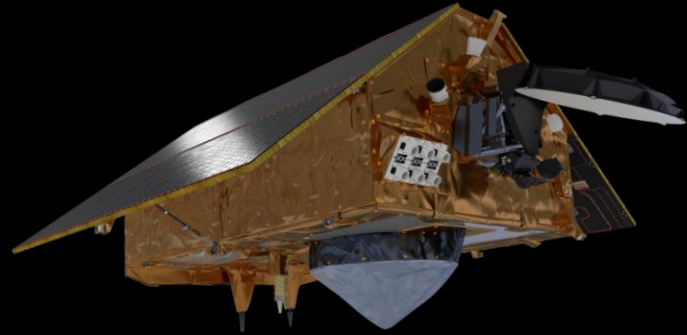


Low-lying coastal zone is home to 680 million people

3 million extra people at flooding risk for every cm of sea level rise

IPCC predictions for 2100 show 0.43 - 0.84 meter increase of average sea levels

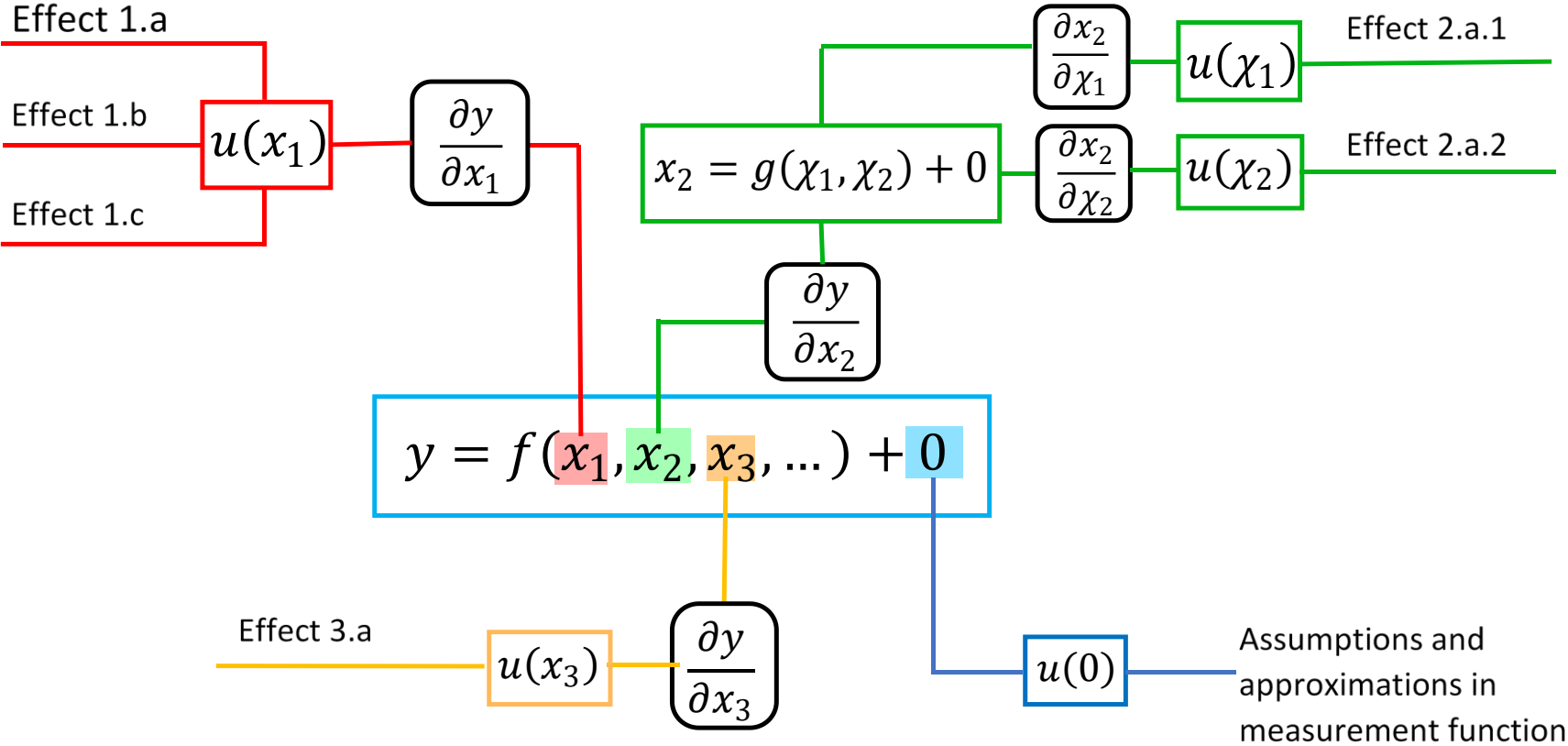
FRM: Sentinel-6 and Jason-3 Tandem flight



30 seconds (~220 km)
The tandem flight lasted 12 months

Decision in August '21 to cross-calibrate the Side B of the POS-4 against Jason-3, to ensure the continuation of the 30-year Global Mean Sea Level record
Both A-side and B-side instrument chains commissioned successfully.

Methodologies – Uncertainty Tree Diagram



$$V(t_p, s) = \frac{\lambda_0}{(4 \cdot \pi)^{\frac{3}{2}} L_{\text{atm}}(s)} \cdot \int_{\text{Vol}} \frac{\chi[t_p - t_r(\zeta, s)] G(x, y, s) R(x, y, \zeta)}{r^2(\zeta)} \exp[-i2\pi(f_0 + f_d) \cdot t_0 + \phi_0] dx \cdot dy \cdot dz + n(t_p)$$

$|V(t_p, s)|^2$ Squared

$\langle |V(t_p, s)|^2 \rangle$ Multilook

$$P_{\text{ML}}(t_p) = \frac{\lambda_0^2}{(4\pi)^3 L_{\text{atm}}^2} \cdot \int_{\text{Vol}} \frac{|\chi[t_p - t_r(z)]|^2 G^2(x, y) \sigma_0(x, y, z)}{r^4(z)} dx \cdot dy \cdot dz + N(t_p)$$

Assumption 1: Far Zone

approximation due to far-zone =>

$$\frac{1}{r^4(z)} \approx \frac{1}{H^4}$$

Assumption 3: Gaussian Ocean

$\sigma_0(x, y, z)$ assumed to be gaussian with skewness of 0.1

$$\sigma_0(x, y, z) = Pu \left\{ \frac{1}{\sqrt{2\pi}\sigma_z} \exp\left(-\frac{z^2}{2\sigma_z^2}\right) \left[1 + \frac{\lambda_s}{6} \left(\frac{z^3}{\sigma_z^3} - \frac{3z}{\sigma_z} \right) \right] \right\}$$

$\gamma_s = 0$ assumed E.M skewness Assumption 3b

$$\sigma_0(x, y, z) = Pu \left\{ \frac{1}{\sqrt{2\pi}\sigma_z} \exp\left(-\frac{z^2}{2\sigma_z^2}\right) \left[1 + \frac{\lambda_s}{6} \left(\frac{z^3}{\sigma_z^3} - \frac{3z}{\sigma_z} \right) - \frac{\gamma_s}{3} \left(\frac{z}{\sigma_z} \right) \right] \right\}$$

σ_z is sea surface height and $SWH = 4\sigma_z$ Gaussian distribution of ocean heights

Pu is amplitude of waveform and used to derive backscatter coefficient $\sigma_0(x, y, z)$

λ_s (ocean topography skewness) is given in input as 0.1

Assumption 2: Antenna Pattern

$\theta_{3\text{dB}}$ is 3dB antenna pattern aperture (characterised on ground)

ξ^2 is the squared antenna mispointing

G_0 is the antenna Gain at boresight (characterised on ground)

$$G_0^2 \exp\left\{ -\frac{8\ln(2)}{\theta_{3\text{dB}}^2} (\theta^2 - \xi^2) \right\}$$

$G^2(x, y)$ assumed to be **gaussian and isotropic** ($\theta_{x3\text{dB}} = \theta_{y3\text{dB}} = \theta_{3\text{dB}}$):

Assumption 4: Point Target Response

$|\sin c|^2$ approximated as gaussian with std σ_t

$$|\chi[t_p - t_r]|^2 = |\sin c[B_r(t_p - t_r)]|^2 \approx \exp\left[-\frac{1}{2\sigma_t^2} (t_p - t_r)^2\right]$$

$$P_{\text{ML}}(t_p) = \frac{\lambda_0^2}{(4\pi)^3 L_{\text{atm}}^2 \cdot H^4} \cdot \left(\int_{\text{Vol}} |\chi[t_p - t_r(z)]|^2 G^2(x, y) \sigma_0(x, y, z) dx \cdot dy \cdot dz \right) \cdot \text{gamrnd}\left(L, \frac{1}{L}\right) + N(t_p)$$

(E. Wooliams)

$$P_{\text{ML}}(t) = A \exp(-v_1) \cdot [1 + \text{erf}(u_1)] - \frac{A}{2} \cdot \exp(-v_2) [1 + \text{erf}(u_2)]$$

Propagating Uncertainties and Error Correlation Structures through Retracking and Sea State Bias Correction

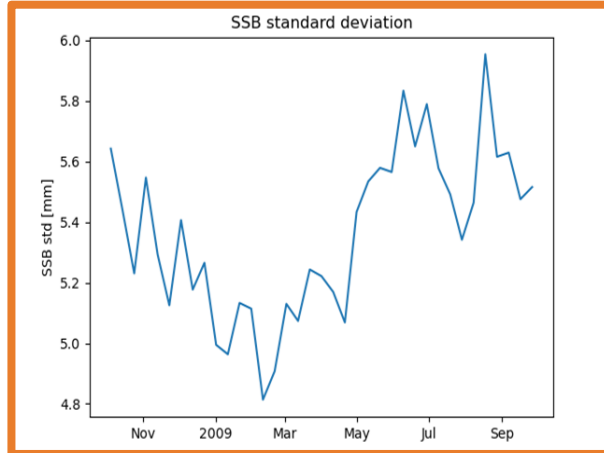
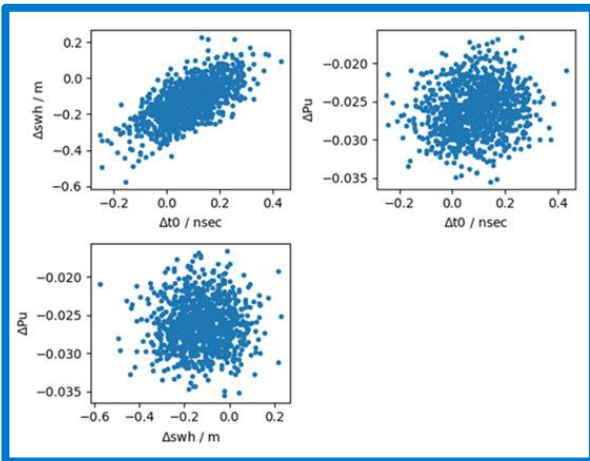
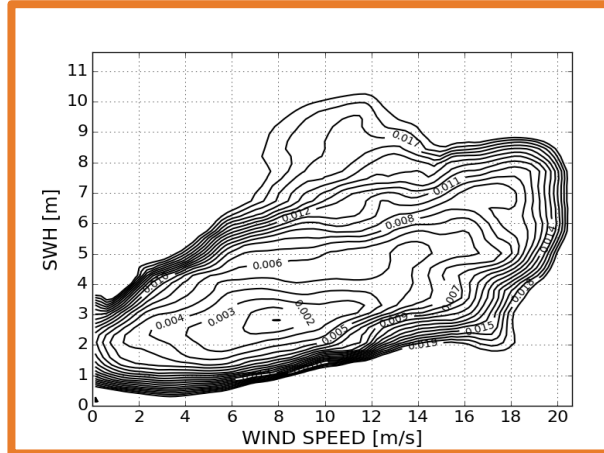
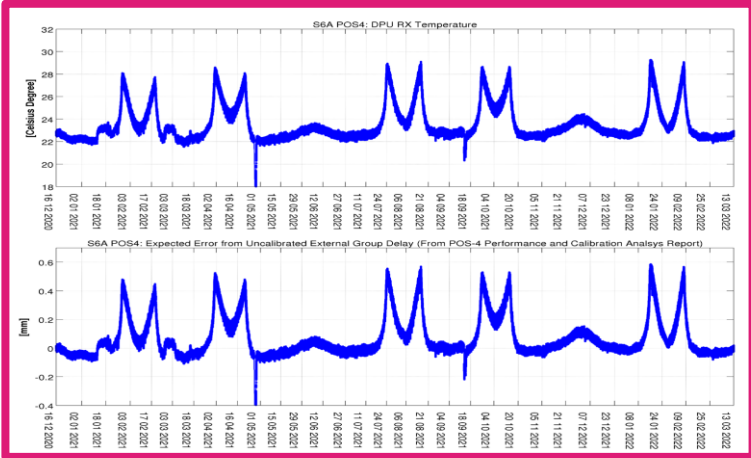
Sajedeh Behnia^a, Jonathan Mittaz^{a,b}, Hannah Cheales^a, and Emma Woollams^a

^aNational Physical Laboratory and ^bReading University



National Physical Laboratory
2022 Ocean Surface Topography Science Team (OSTST) meeting

ESA ASELISU Study



Introduction

What is the uncertainty budget in deriving Global Mean Sea Level (GMSL) from satellite altimetry? This is one of the questions to be addressed within the framework of the ESA Master project Assessment Sea Level the Quality Uncertainty Assessment (ASELSU). ASELSU addresses this question in a methodical manner which entails a full breakdown of all sources of uncertainties arising from the estimator and assessment of error correlation structures to quantify the uncertainty budget.

From acquiring the radar backscatter to forming a waveform and estimating the GMSL, several processing steps are involved, which makes the uncertainty analysis intricate. This is especially so considering the components such as the atmospheric range and sea state bias correction are not derived independently. Four primary parameters – epoch, sigma-0, significant wave height and re-tracking angle – are derived from the most common retracking used (ML04 (Arnould et al., 2004)). Two of these parameters, sigma-0 and significant waveheight, are used to estimate the wind speed, which in turn is used with significant waveheight (sgwh) to determine the sea state bias correction.

In the current study, we perform simulations to understand the extent of possible error correlations between different quantities derived from the ML04 retracker, and propagate these through to sea state bias and topographic correction.

Simulation

Our simulation aims at identifying and characterizing error correlation structures between intermediary parameters which () are affected by the uncertainties of the instrumental component of an altimetry system, and eventually it reflect the uncertainty of the Global Mean Sea Level product. We:

1. simulate LRIM waveforms of Sentinel-6 Michael Freilich;
2. vary normal and specific noise levels to generate a set of inputs for Monte Carlo analysis;
3. retrack the waveforms using ML04;
4. derive σ_0 , U , SSB_{sea} , SSB_{atm} , and IC ; and
5. investigate relevant correlation structures.

Our simulation shows moderate to strong correlations between the pairs (SSB_{sea}, IC) , (SSB_{atm}, R_{sea}) , and (SSB_{atm}, R_{atm}) , and significant correlations for (R_{sea}, IC) and (SSB_{atm}, SSB_{sea}) . See figures.

Conclusion

GOOS has established new stability uncertainty requirements on σ_0 and U to address scientific need to reliably climate change. One aim of ASELSU is to identify whether or not instrumental improvements are needed for Sentinel-6. Final scientific advisory releases to meet the new scientific requirements.

acknowledgement

This study is carried out as part of the ESA-funded project ASELSU. The content is developed in collaboration with other project members, Magellium, LEGOS, and CLS.

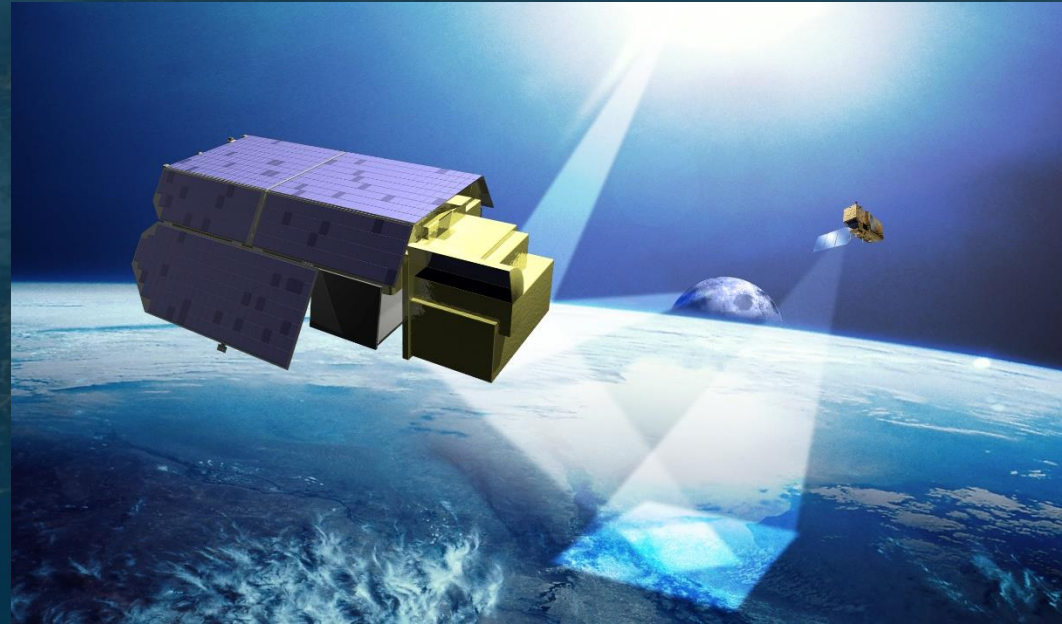
We especially thank Salvatore Chirvito, Adrien Guerot, Sebastian Figueras, and Pagan Trian for their valuable scientific support. CLS has provided us with the ML04 retracker and look up tables for deriving wind speed and sea state bias.

This work is partially funded by the project Metology for Earth Observation and Climate, MetEO4. Coordinated by NPL, MetEO4 is series of collaborative European metology projects supporting Earth Observation applications.



Traceable
Radiometry
Underpinning
Terrestrial- &
Helio-
Studies

An ESA EarthWatch mission



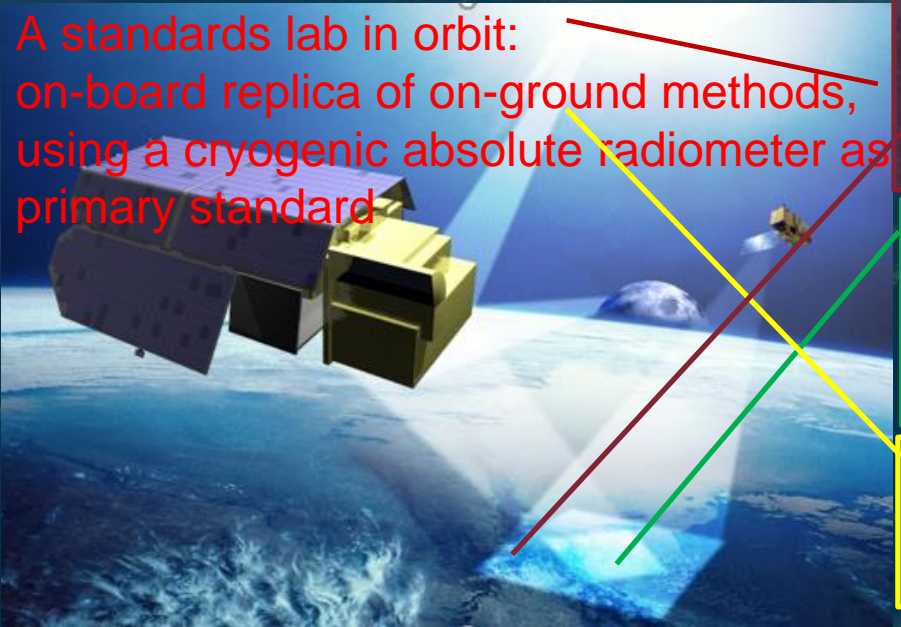
A 'gold standard' reference in space to support the climate emergency

SITSats and TRUTHS Mission Objectives

What is a SITSat?: 'Space borne missions specifically designed, characterised and documented to provide **high accuracy SI-Traceable** 'reference' measurements.' (Evidencing comprehensive uncertainty to SI, 'in-space', of all contributors to observations made from the satellite)

TRUTHS is an **operational climate mission**, that will enable:

A standards lab in orbit:
on-board replica of on-ground methods,
using a cryogenic absolute radiometer as
primary standard



1. **Climate benchmarking:** enhance our ability to estimate the **Earth Radiation Budget** (and attributions) through direct measurements of incoming & outgoing energy and reference calibration of other ERB & similar missions.

2. **Satellite cross-calibration:** establish a 'standards laboratory in space' to create a '**gold standard**' reference data set to cross-calibrate other sensors and improve the quality and interoperability of their data through: simultaneous observations, surface reference sites and the moon

3. provide SI-traceable measurements of the **solar spectrum (incoming & reflected)** to address its impact on climate and interactions with the atmosphere and surface

A **benchmark measurement** is one with characteristics (documentation, SI-Traceable uncertainty, representative sampling) that allows it to be unequivocally considered a 'reference' of the specified measurand against which future measurements of the same measurand, can be compared.

Conclusion

- **Climate data records from satellites** are a fundamental at ESA – **we are committed** to deliver *Climate Space*
- **Metrology is essential** due to the overwhelming volume of data from space: small errors have major impacts on climate time series
- We are **embedding Metrology** (uncertainty and traceability) into all of our satellite engineering and scientific processes:
 - In our satellite designs and data processing
 - Via Fiducial Reference Measurements (FRM) for validation
 - For our flying constellations using tandem flights
 - In new SITSat missions dedicated to SI traceability (e.g. TRUTHS)
 - By implementing QA4EO uncertainty modelling techniques

ESA recognises the essential role of the International System of Units (SI) in providing confidence in the accuracy and global comparability of measurements needed for protection of the environment, global climate studies and scientific research

Thank you Any Questions?

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Craig.Donlon@esa.int

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