

Requested reliability of dynamic mechanical measurement in mobility, from automobile to service robot

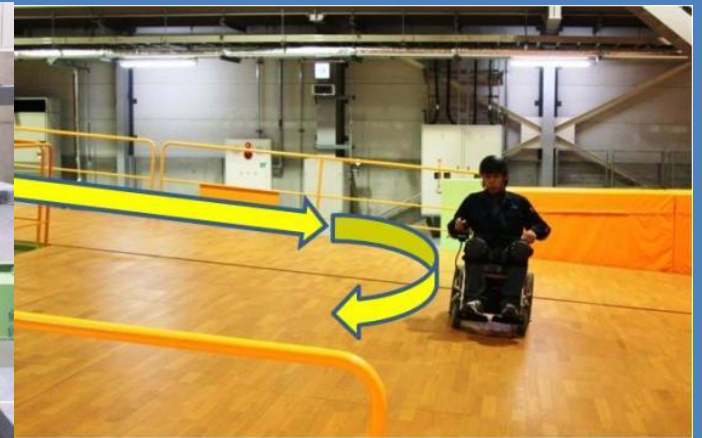
Tatsuo Fujikawa

Japan Automobile Research Institute (JARI)

Japan Automobile Research Institute

➤ JARI: Independent lab. for automotive research & test in Japan

- ✓ Research and testing on automotive safety and environment
- ✓ Expanding our research and testing field to safety of robotics in terms of interactions with human
- ✓ In this presentation, dynamic measurement methods for collision of cars and robots will be reported and discussed.



Contents

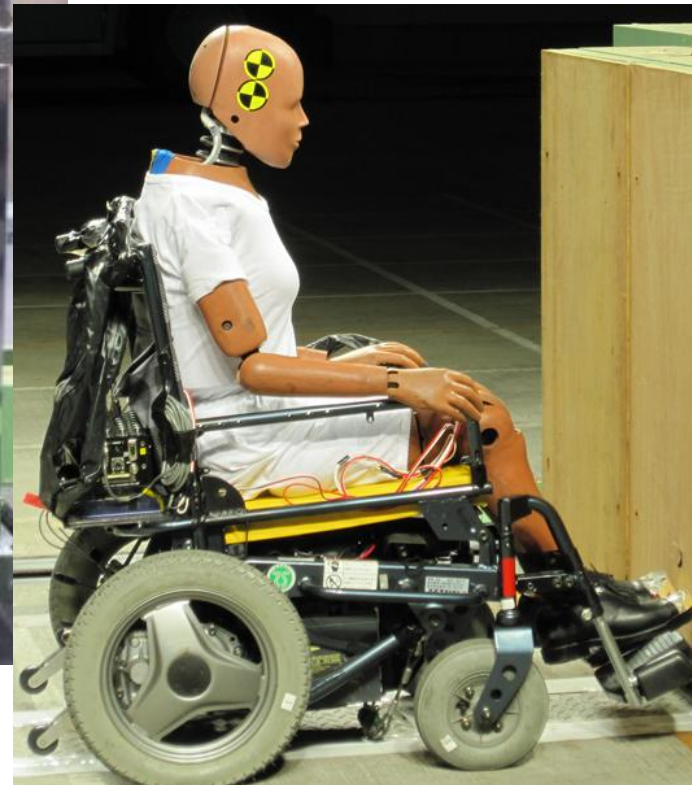
- **Collision tests of personal care robots**
- **Car crush criteria**
- **Car crush dummy**
- **Calibration of sensors**
- **Required dynamic response (Examples of data)**
- **Dynamic measurement in our studies**

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Collision tests of personal care robots

Project for practical applications of service robots
by New Energy and Industrial Technology Development Organization



Collision tests of personal care robots



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Car crush criteria

Example 1: Rigid barrier / in-position / FMVSS 208

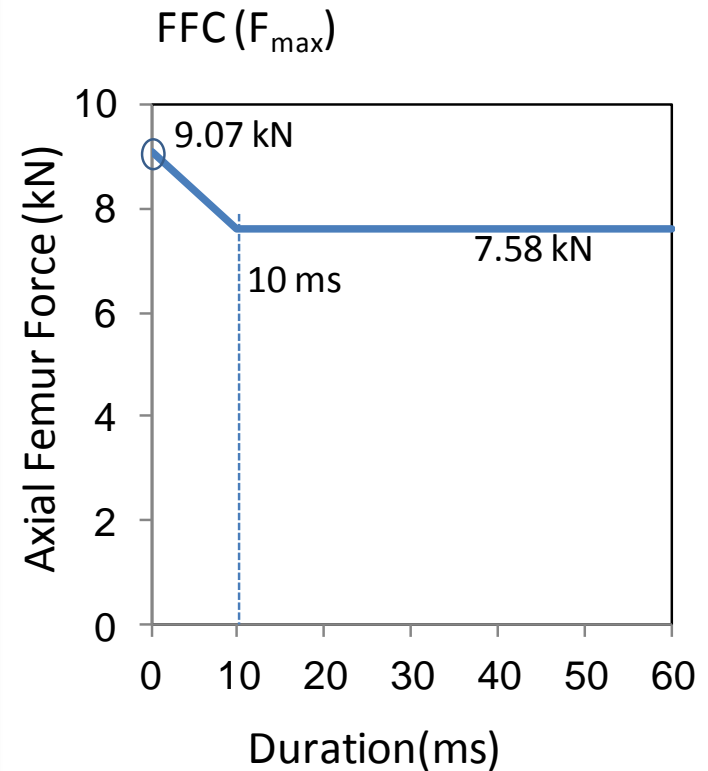
	50 % male	5% female
Head	$HIC_{15} = 700$	$HIC_{15} = 700$
Neck	$N_{ij} = 1.0$ Tension: $Fz_{max} = 4.17 \text{ kN}$ Compression: $Fz_{max} = 4.0 \text{ kN}$	$N_{ij} = 1.0$ Tension: $Fz_{max} = 2.62 \text{ kN}$ Compression: $Fz_{max} = 2.52 \text{ kN}$
Chest	$a_{3ms} = 60 \text{ G}$ $s_{max} = 63 \text{ mm}$	$a_{3ms} = 60 \text{ G}$ $s_{max} = 52 \text{ mm}$
Femur	$F_{max} = 10 \text{ kN}$	$F_{max} = 6.805 \text{ kN}$

$$HIC_{15} = \left[\frac{1}{t_2 - t_1} \int_{t_1}^{t_2} a \, dt \right]^{2.5} (t_2 - t_1)$$

Car crush criteria

Example 2: Deformable barrier / in-position / EC

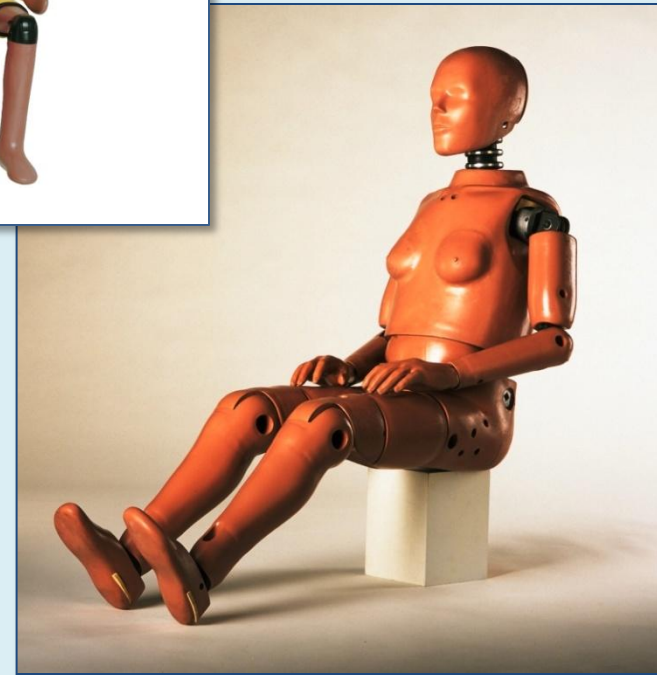
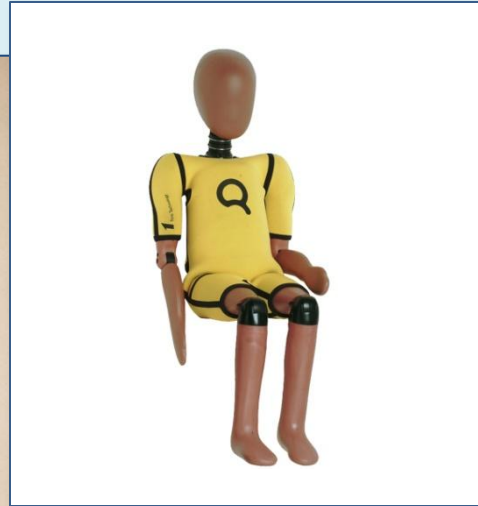
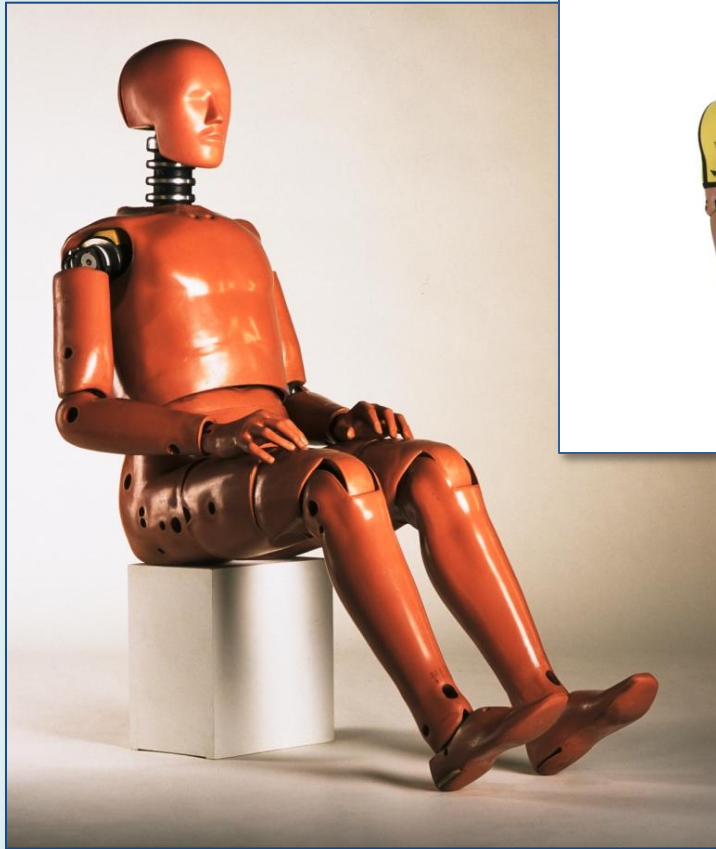
	50 % male
Head	$HPC_{36} = 1000$ $a_{3ms} = 80 \text{ G}$
Neck	$M_y = 57 \text{ Nm}$
Chest	$VC = 1 \text{ m/s}$ $ThCC(s_{max}) = 50 \text{ mm}$
Femur	$FFC (F_{max})$
Knee	$s_{max} = 15 \text{ mm}$
Tibia	$TCFC(F_{max}) = 8.0 \text{ kN}$ $TI = 1.3$



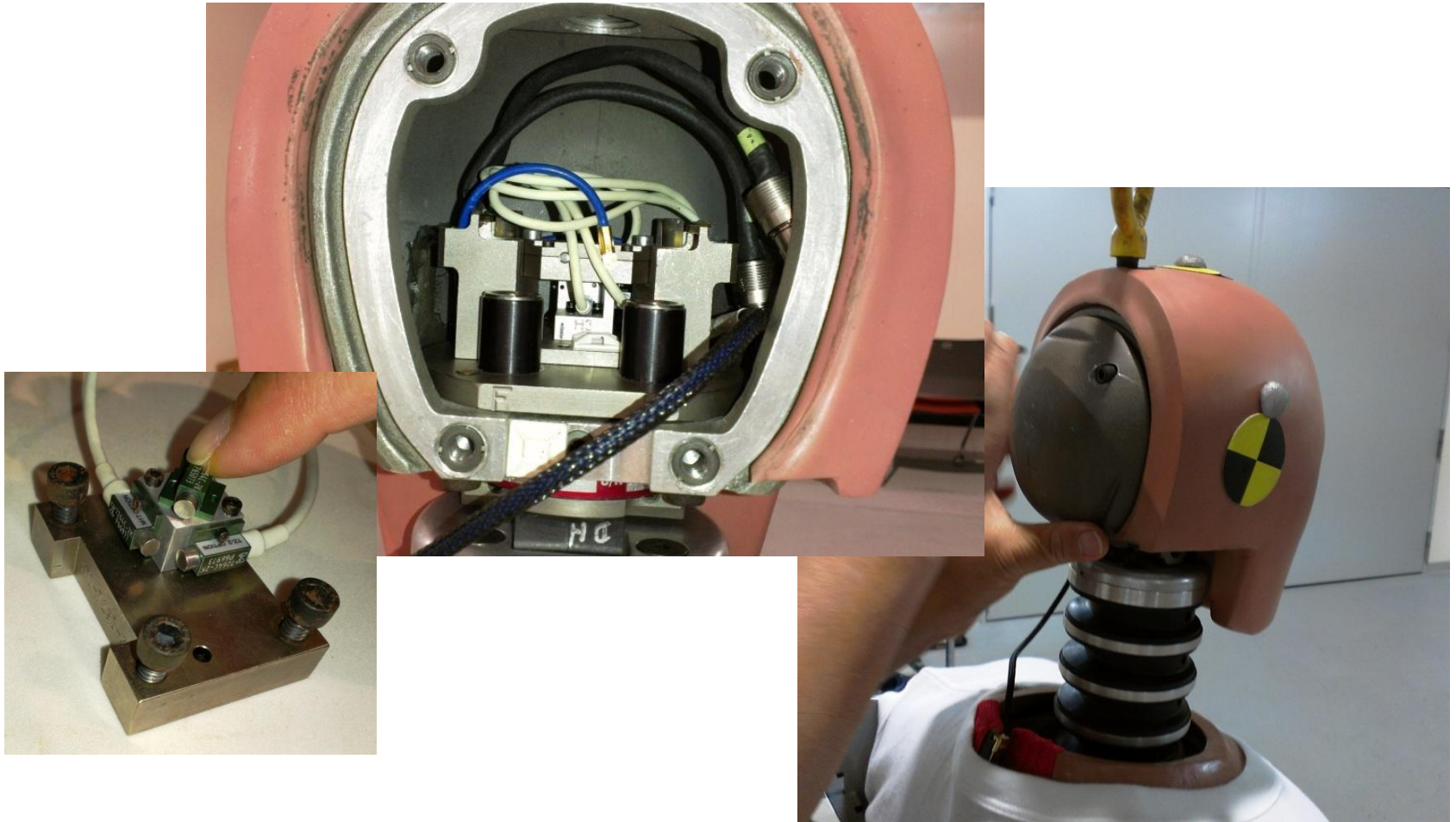
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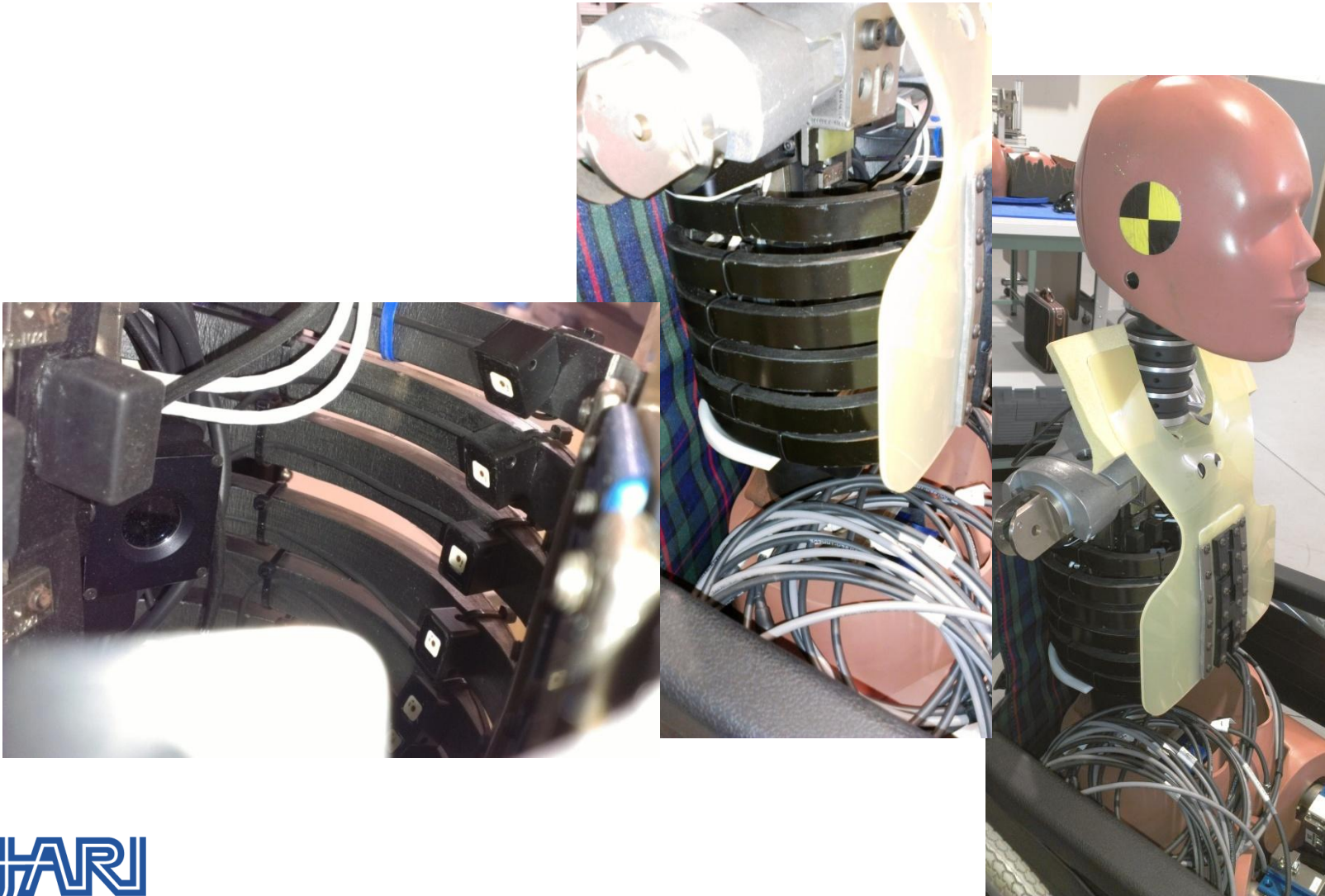
Car crash dummy



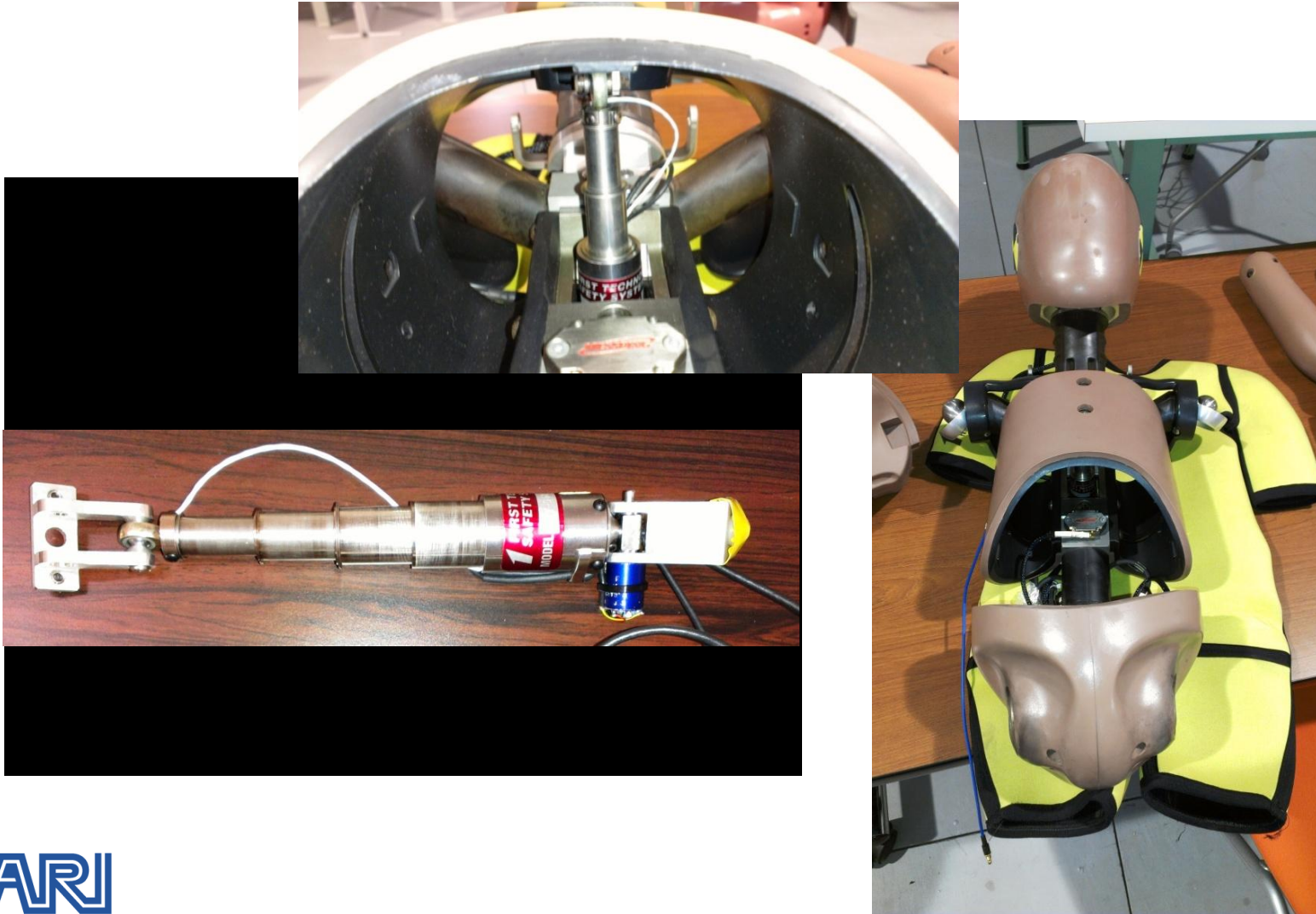
Car crash dummy



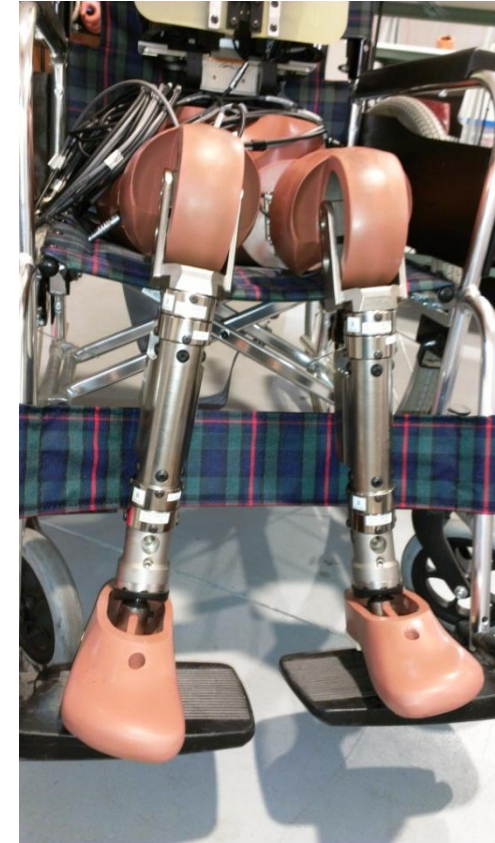
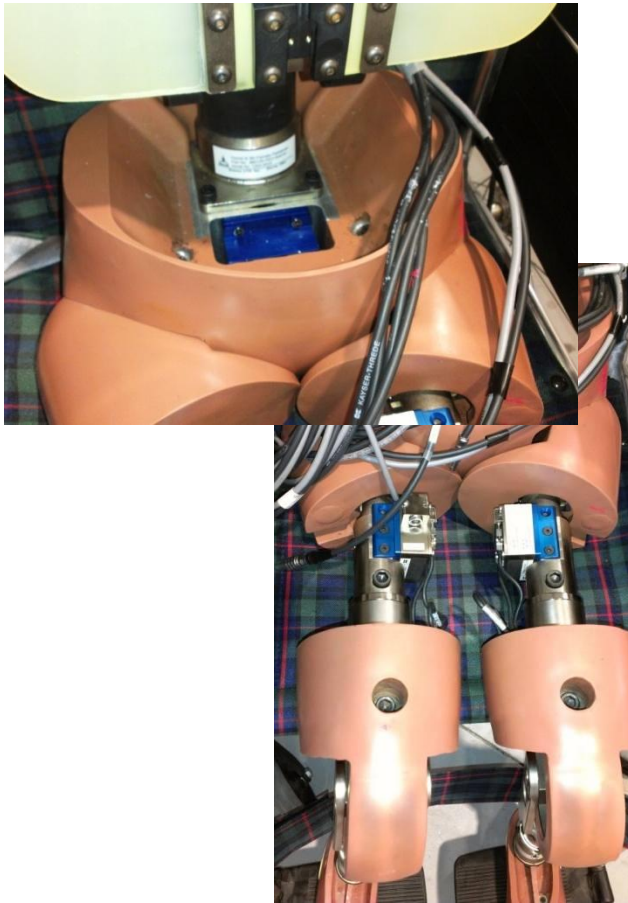
Car crash dummy



Car crash dummy



Car crash dummy



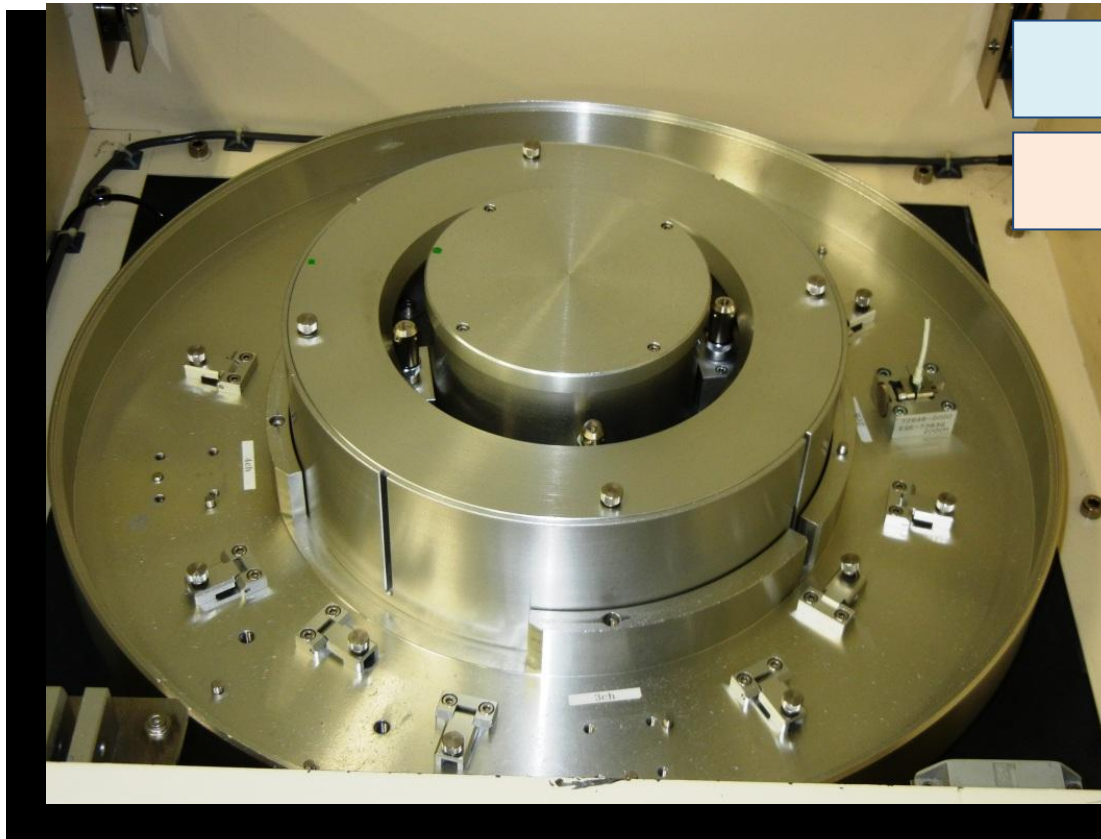
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Calibration of sensors

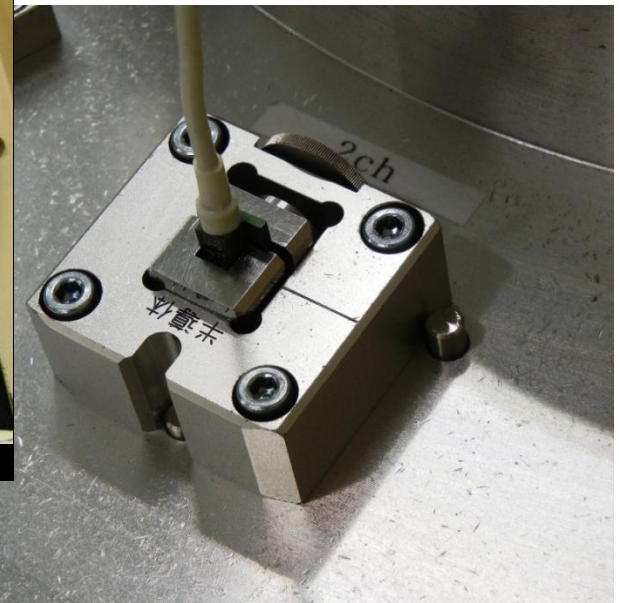
	Static Calibration of sensors	Dynamic Calibration of sensors	Response verification of dummy
Acceleration	✓	improving	✓
Displacement	✓	-	✓
Force	✓	-	✓
Torque	✓	-	✓

Calibration of accelerometer

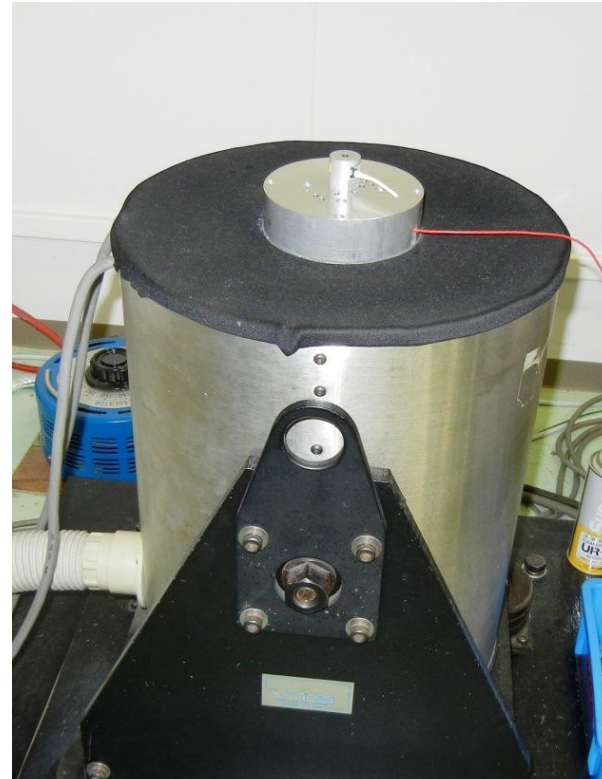
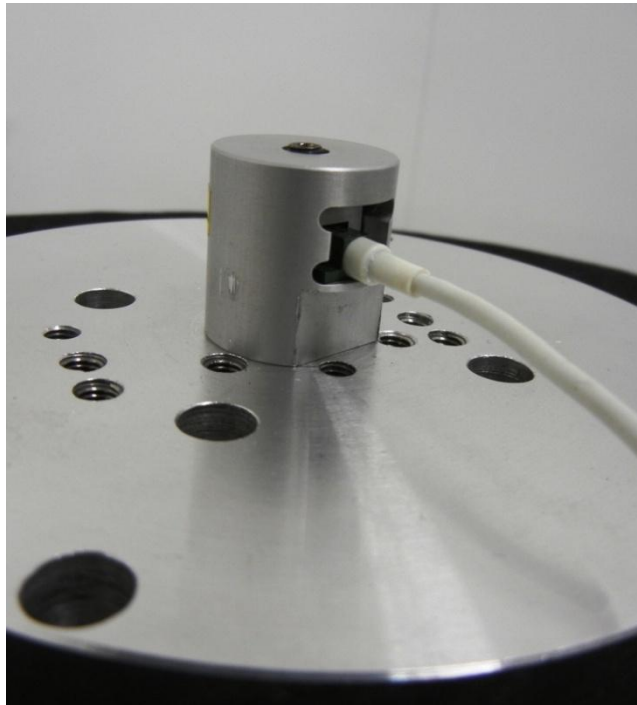


~ 1000 G

Static



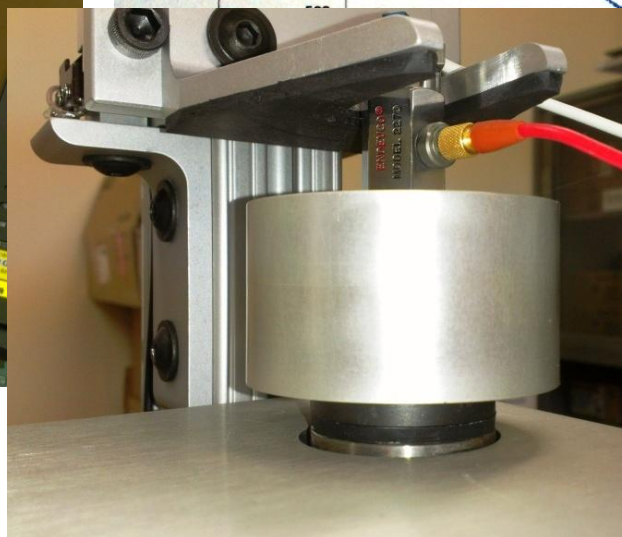
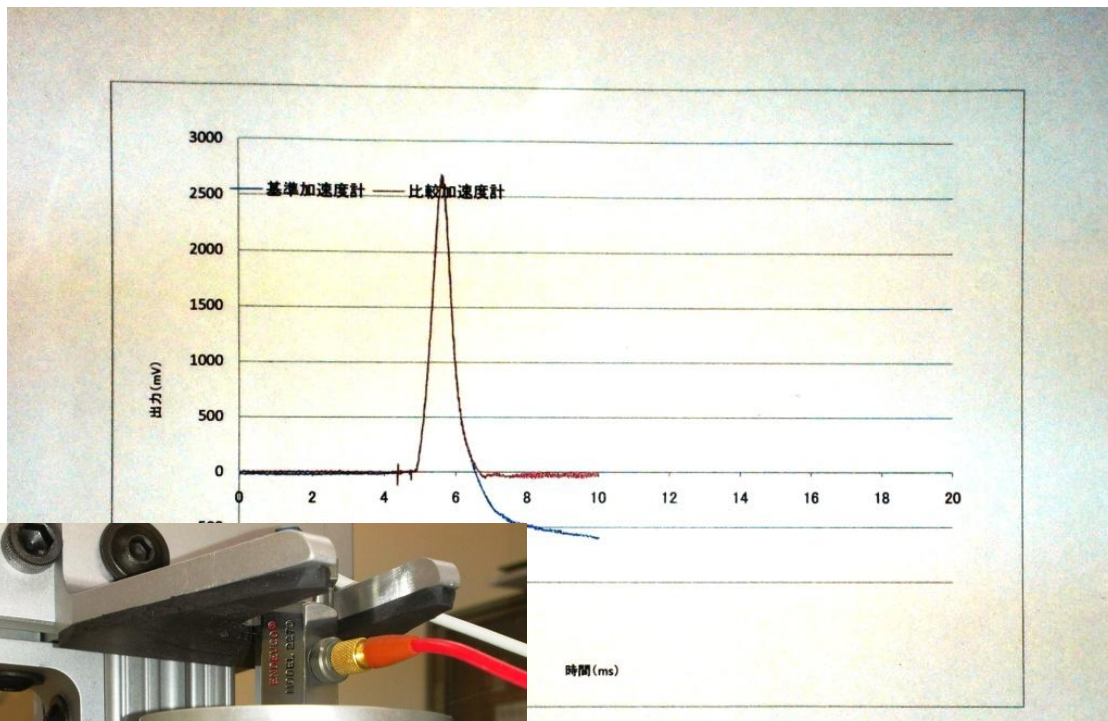
Calibration of accelerometer



Dynamic (up to 2000 Hz)

<10 G

Calibration of accelerometer



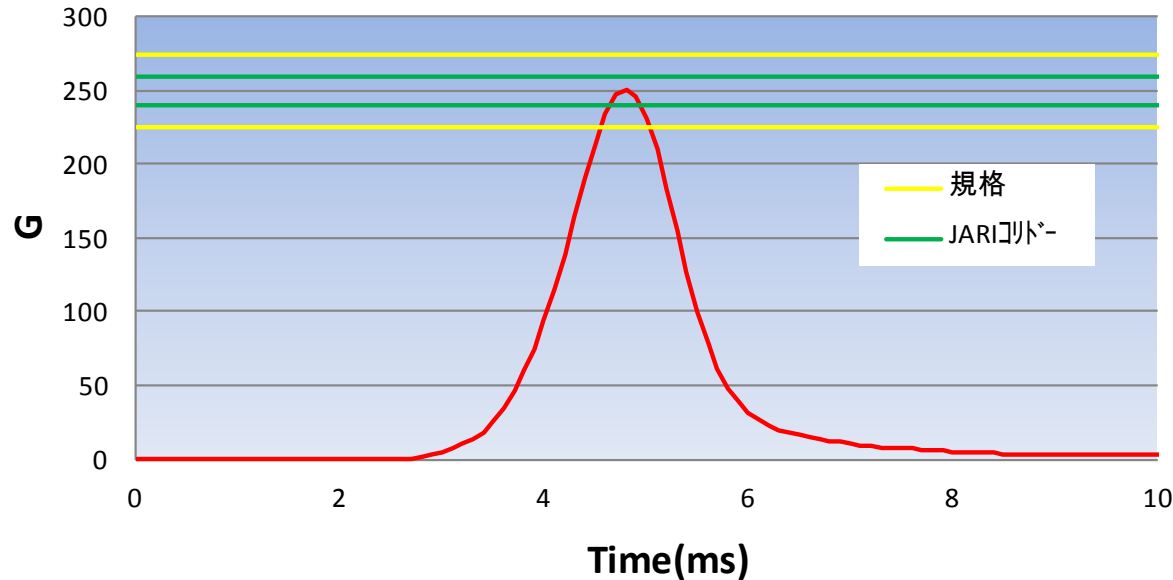
Calibration of force/torque transducer



Static

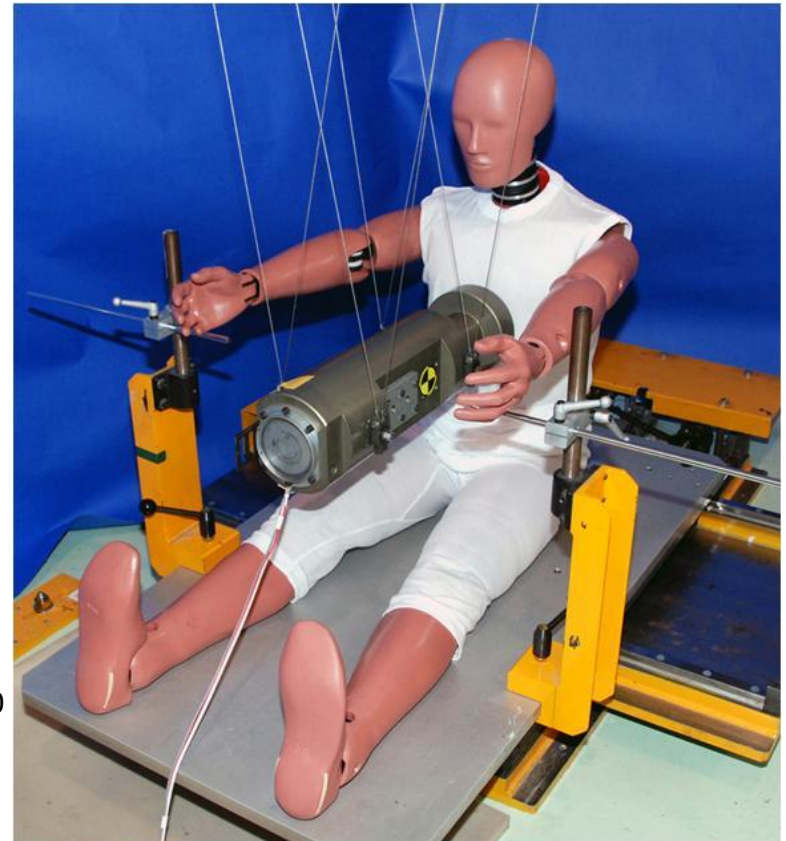
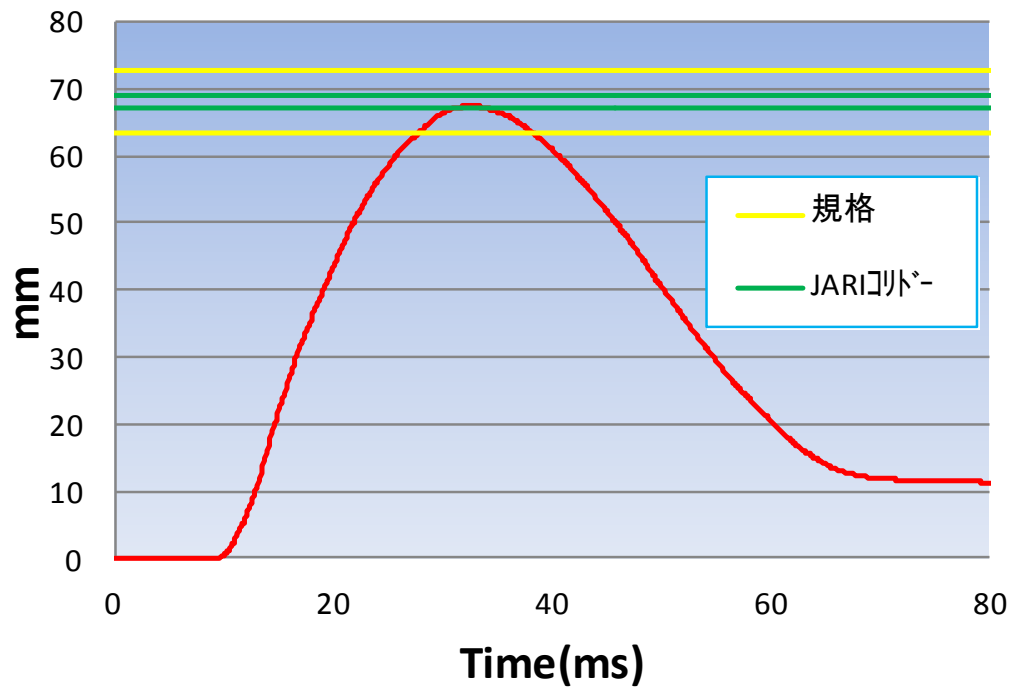
Verification of dummy head response

Resultant Acceleration Hybrid-III 50th



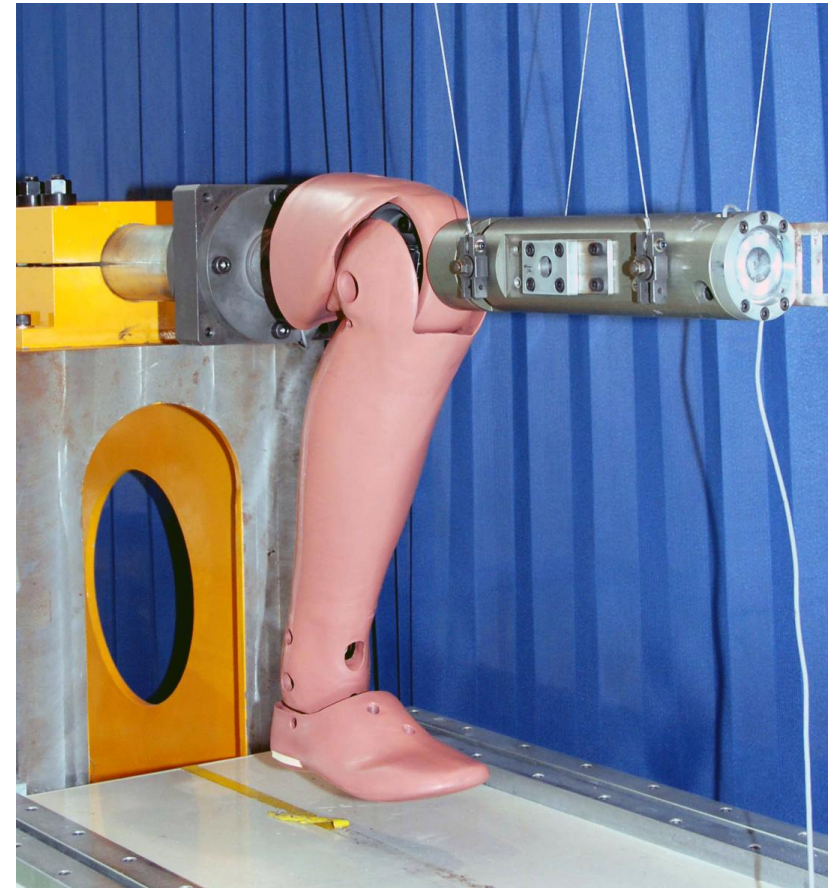
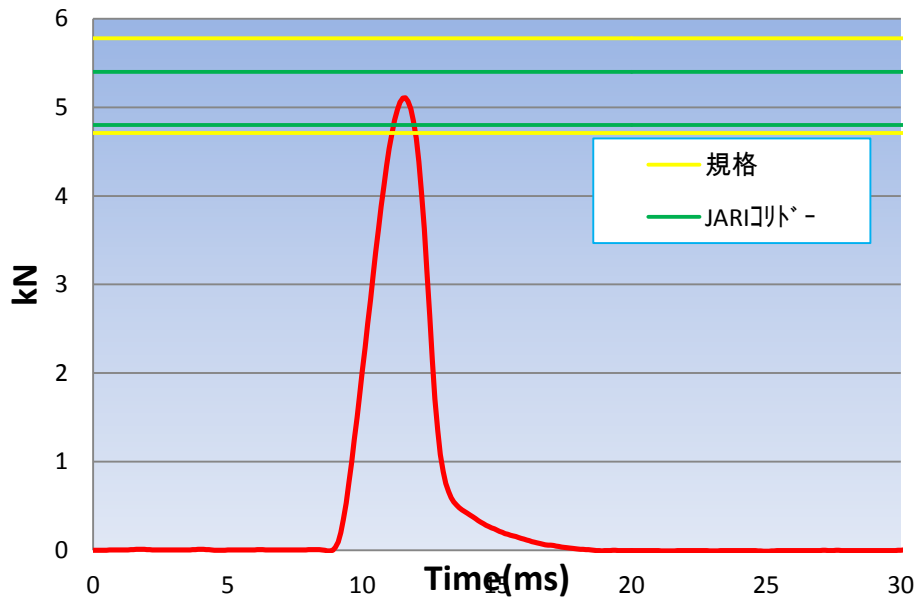
Verification of dummy chest response

Chest Deflection Hybrid-III 50th



Verification of dummy chest response

Knee Impact Force Hybrid-III 50th



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Examples of car crash data

35mph Frontal Impact

$$HIC_{15} = \left[\frac{1}{t_2 - t_1} \int_{t_1}^{t_2} a \, dt \right]^{2.5} (t_2 - t_1)$$

$$HIC_{15} = 518$$

Examples of car crash data

35mph Frontal Impact

Only for Presentation

NEW CAR ASSESSMENT PROGRAM FRONTAL BARRIER IMPACT TEST
NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION

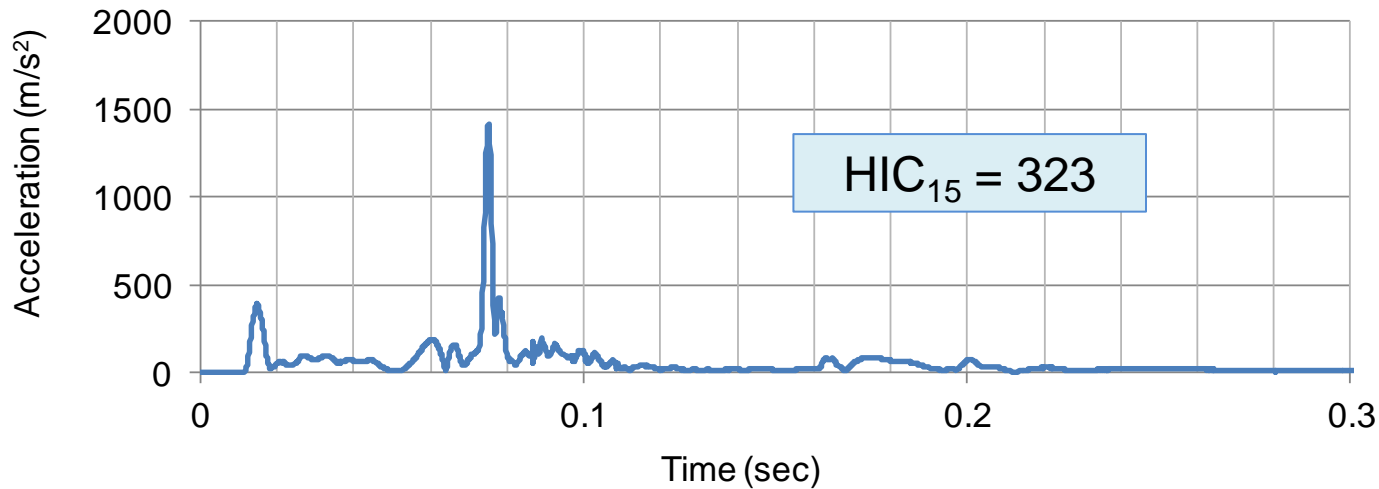
Examples of car crash data

35mph Frontal Impact

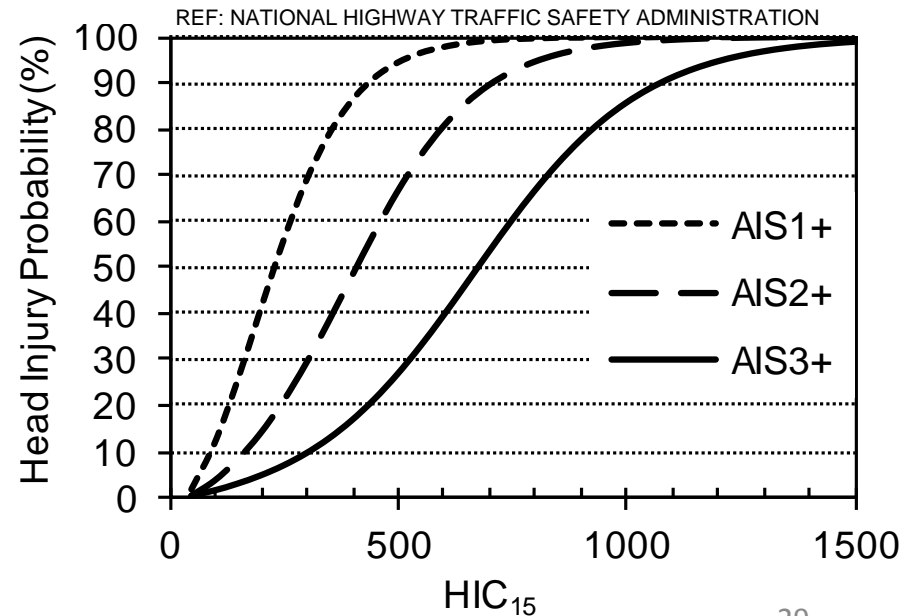
Only for Presentation

NEW CAR ASSESSMENT PROGRAM FRONTAL BARRIER IMPACT TEST
NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION

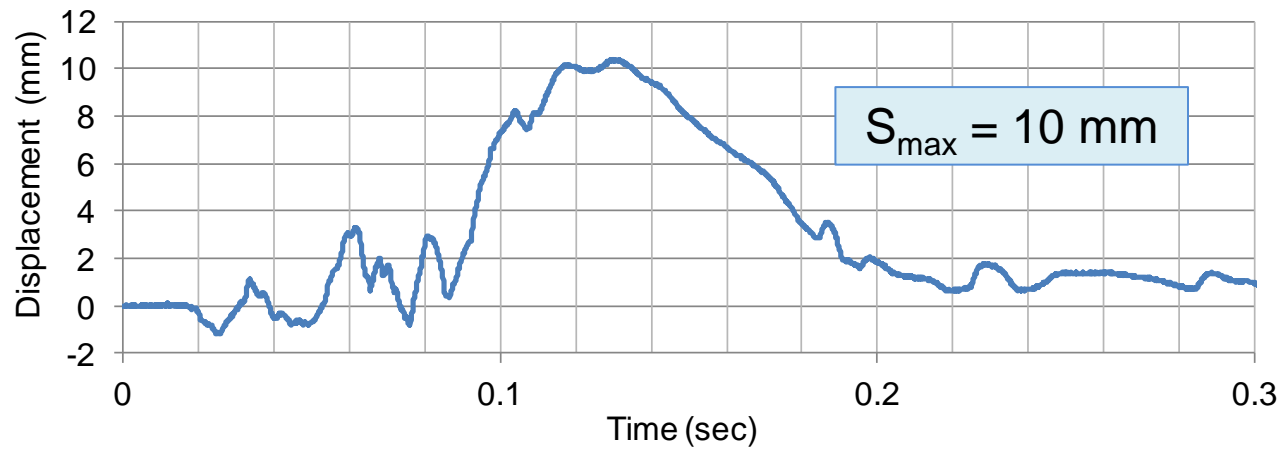
Example of robot crash data



Moving object :
200 kg
Steel Structure
6 km/h
Dummy: 6-Y-O
Standing
in front of wall

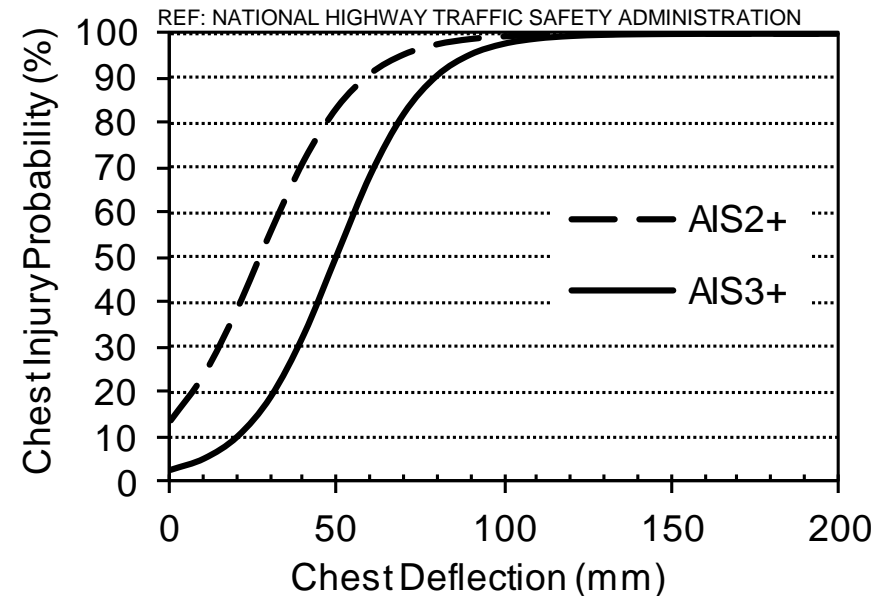


Example of robot crash data



Moving object :
200 kg
Steel Structure
6 km/h

Dummy: 6-Y-O
Standing
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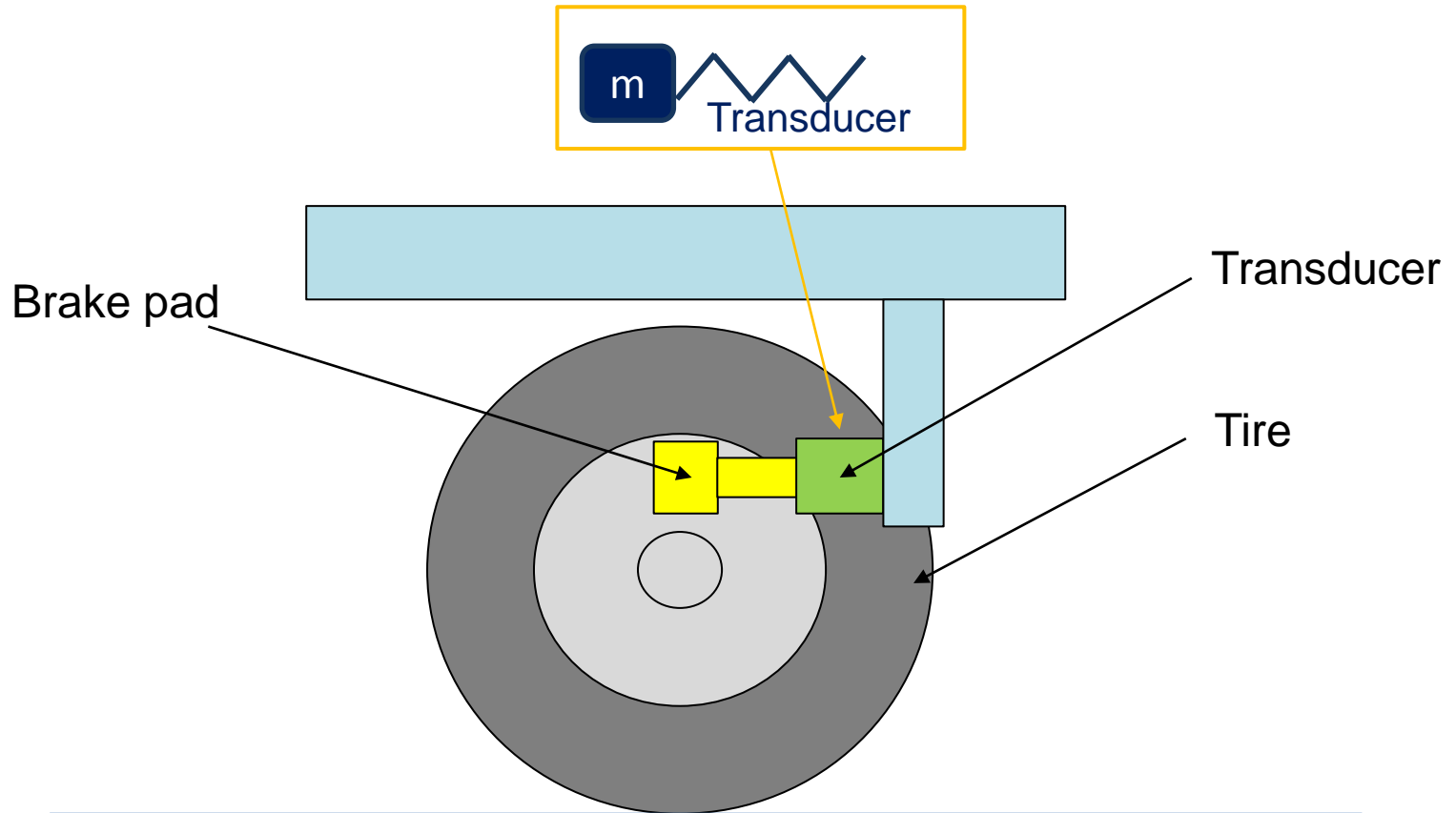


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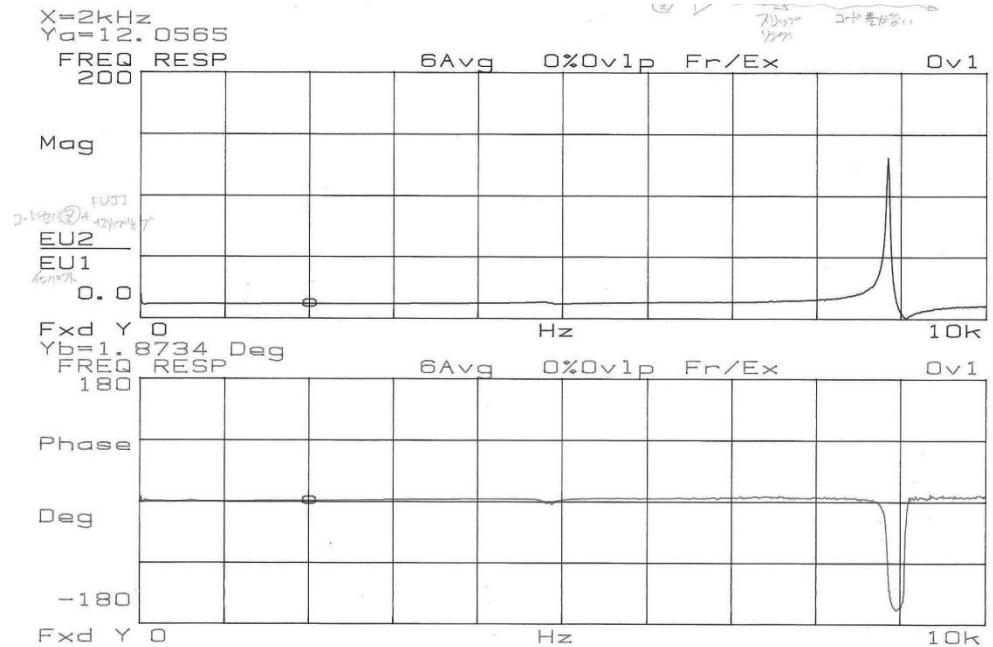
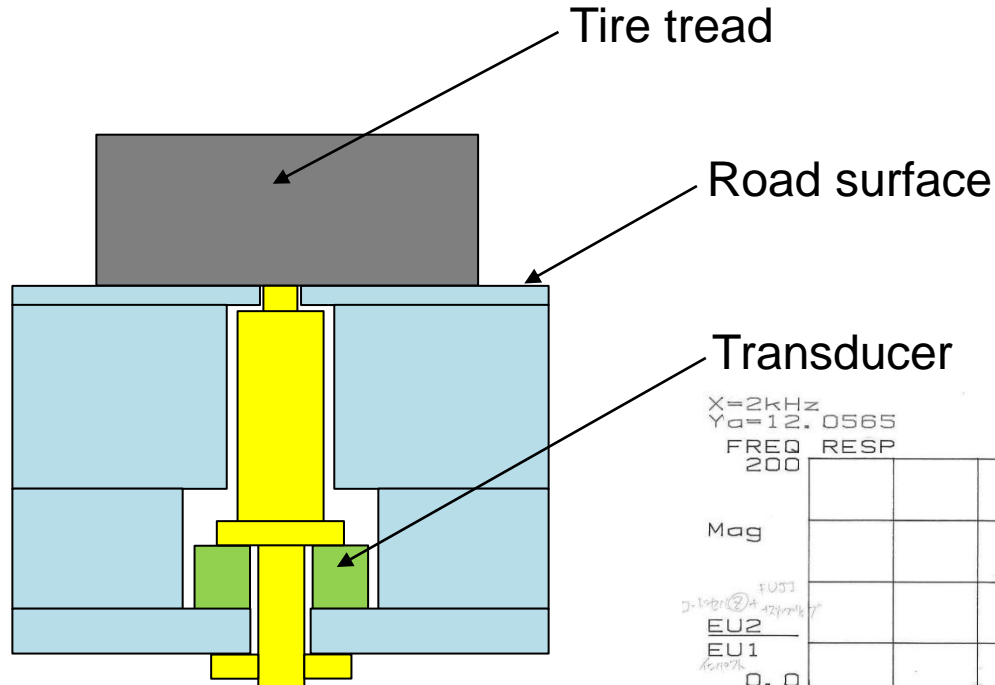
Dynamic measurement

Tire dynamic force /1987



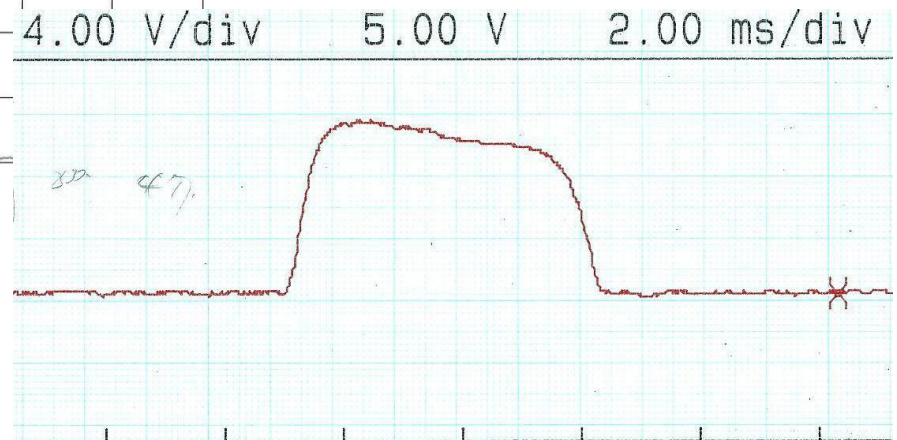
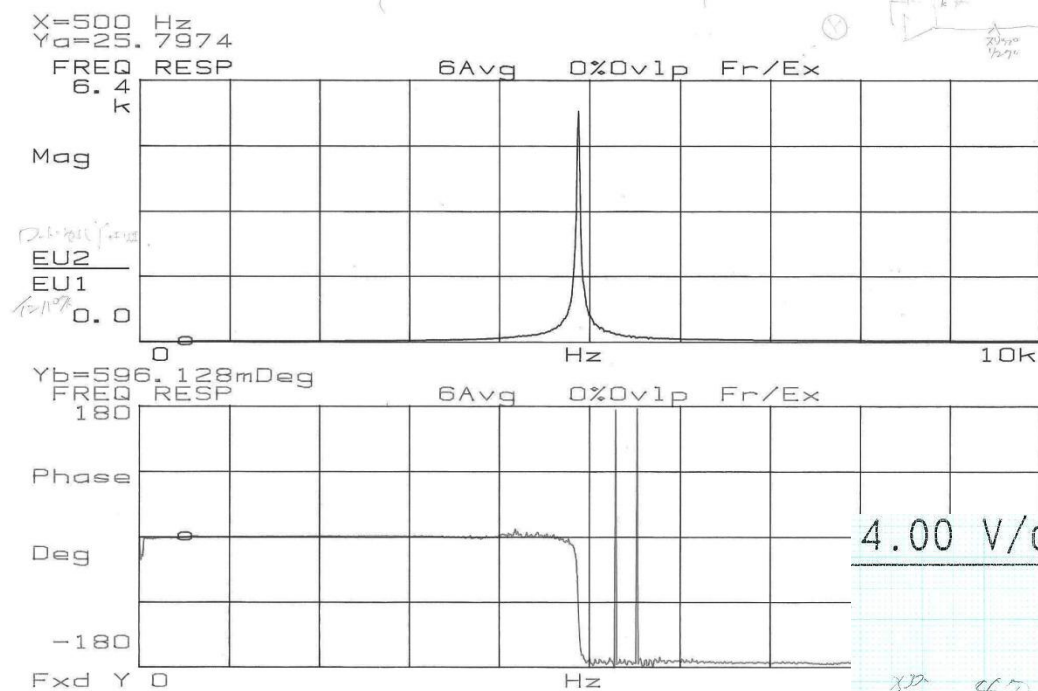
Dynamic measurement

Tire contact force /1989



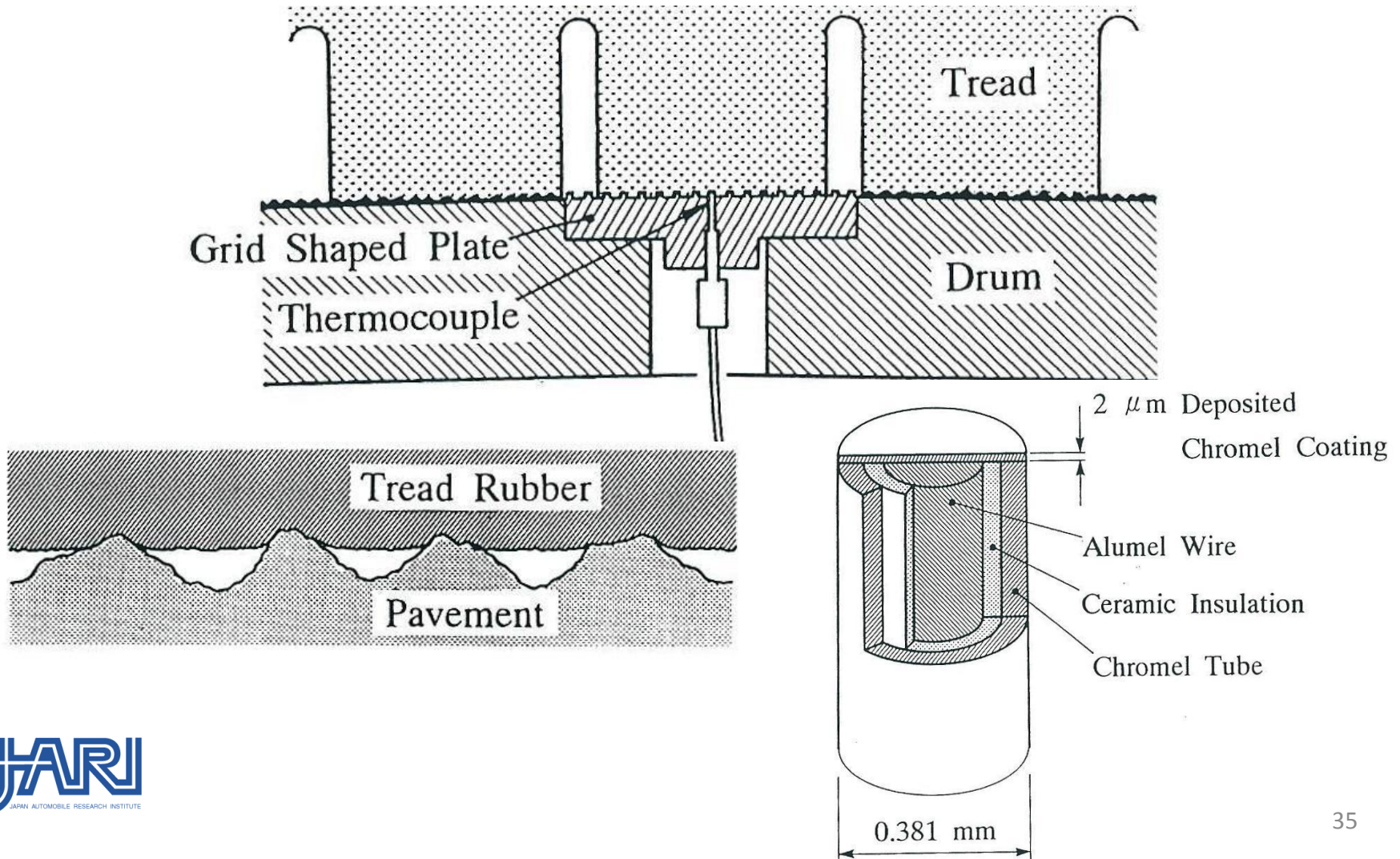
Dynamic measurement

Tire contact force / 1989



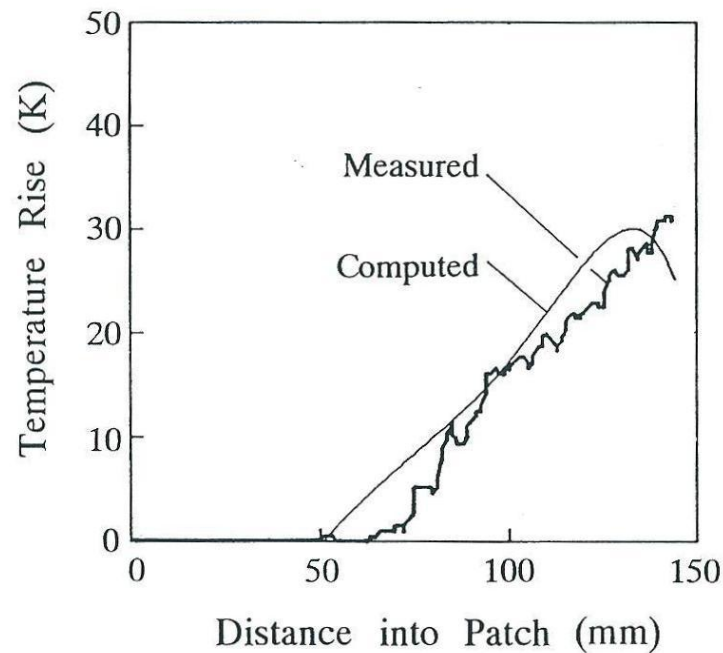
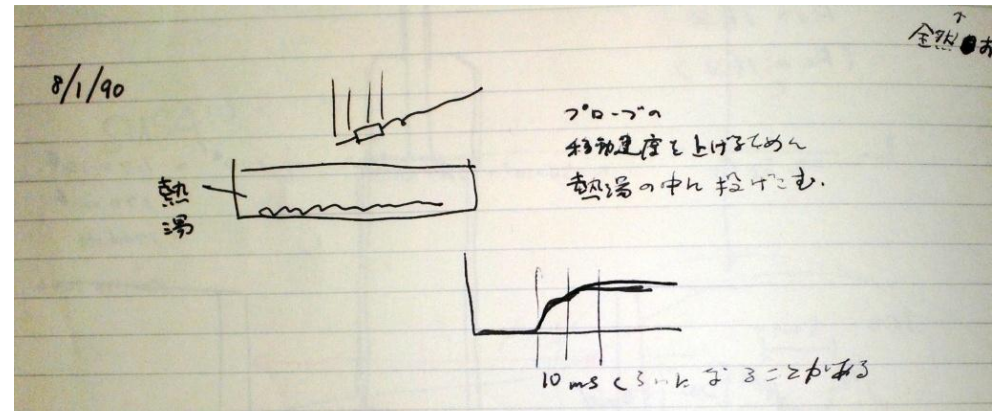
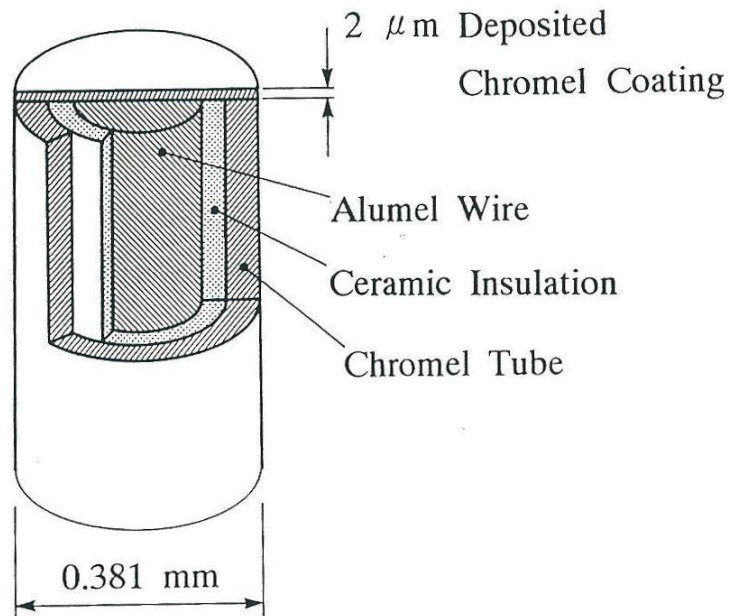
Dynamic measurement

Tire temperature in actual contact area /1990



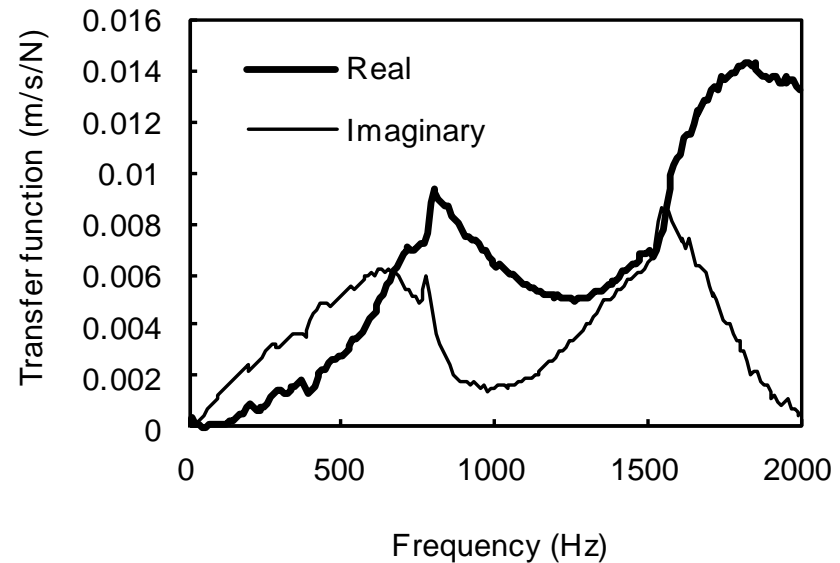
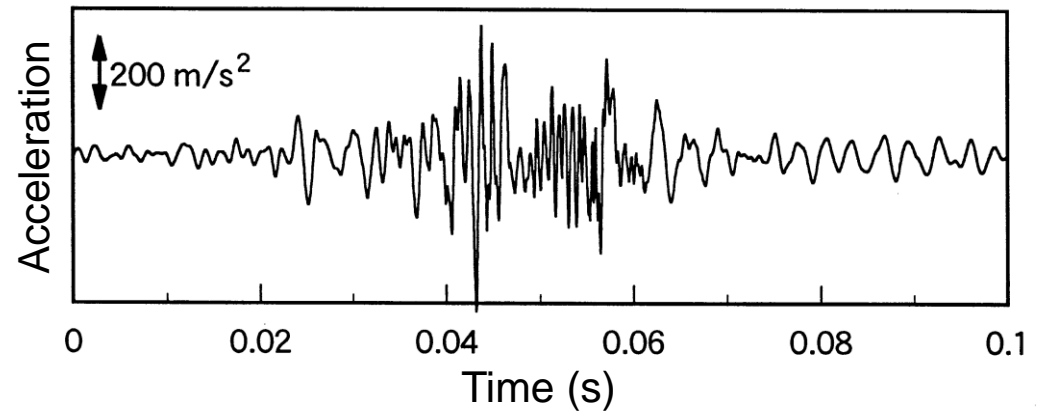
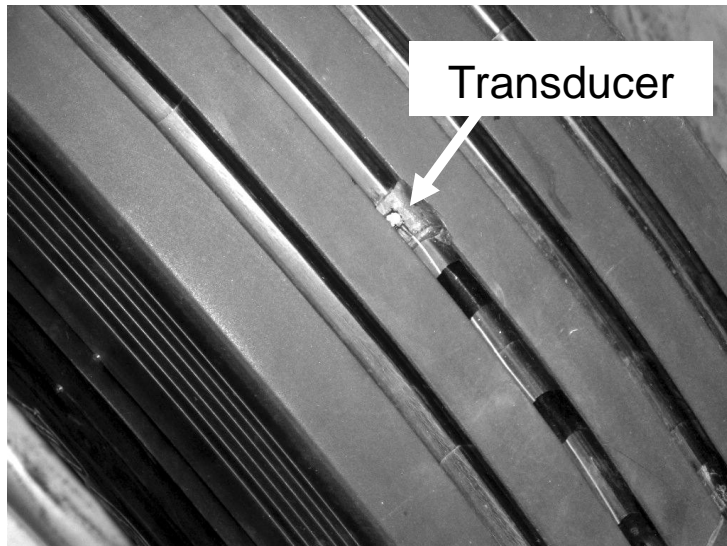
Dynamic measurement

Tire temperature in actual contact area /1990



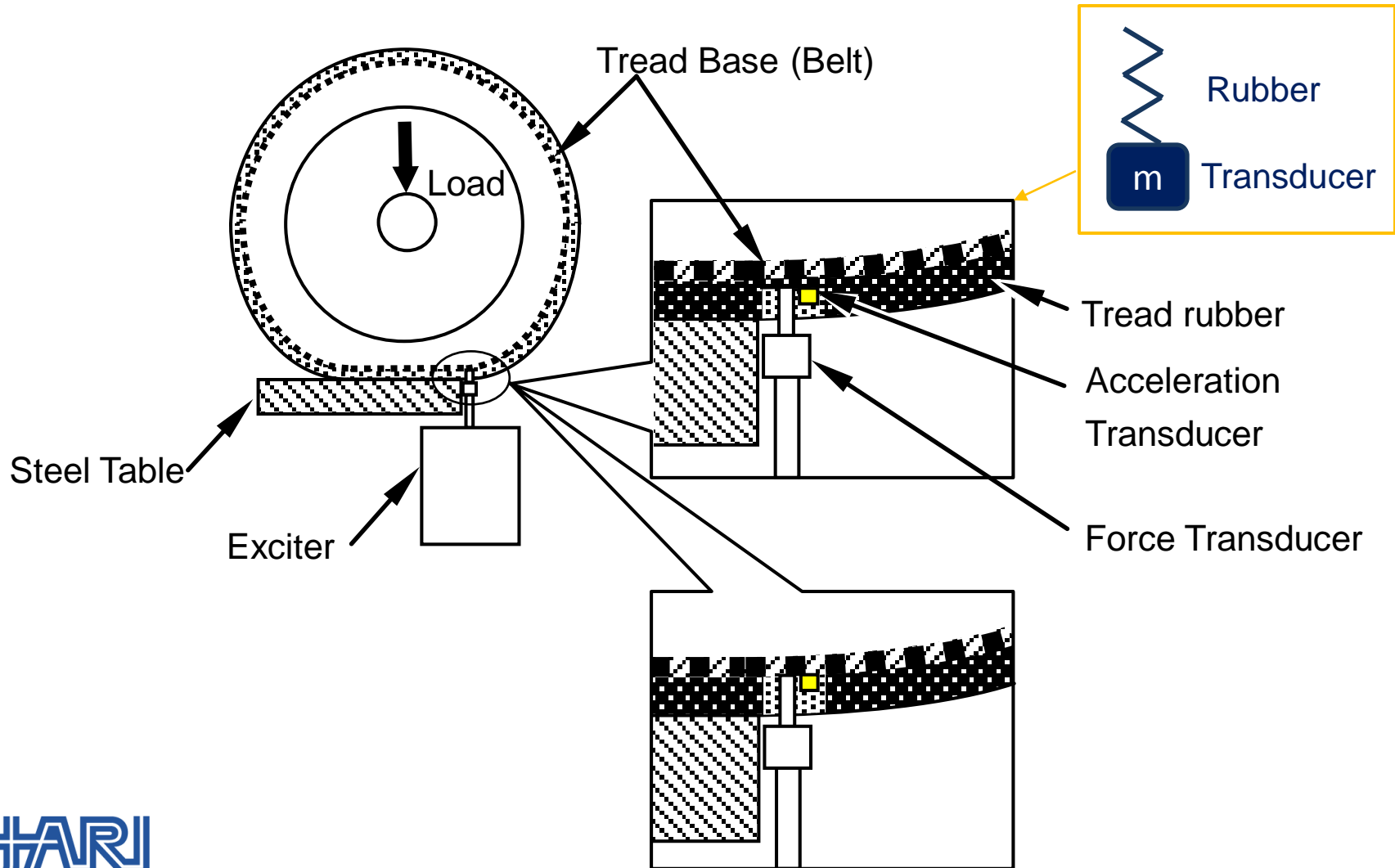
Dynamic measurement

Tire tread vibration /1999



Dynamic measurement

Tire tread vibration /1999



Dynamic measurement

Crash barrier force / 20XX

