KBTM

Kibble Balance
Considerations for Mass and
Gravity

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Introduction



1. Mass:

- a. Process for disseminating mass from the Kibble Balance
- b. Transfer mass selection
- c. Considerations for vacuum to vacuum transfer
- d. Vacuum to air transfer

2. Gravity:

- a. Absolute and Relative Gravimetry
- b. Tide Models
- c. Gravity Transfer

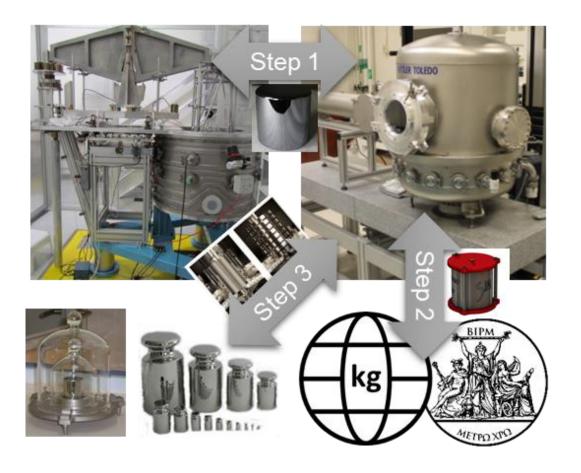
Realization of a Mass value



How do we ensure the mass realized in the balance is the same as the one disseminated out to the world?

Three Steps to mass dissemination from a Kibble Balance





- 1. Realization of the mass of a transfer standard using the Kibble balance
- 2. Transfer standard is used to calibrate traveling standard for participation in ongoing key comparison for CV-kg

And/Or

3. The value of the transfer standard is disseminated from vacuum to air to calibrate national standards that maintain the mass unit at NRC between realizations.

STEP 1: Considerations for KB mass artefacts



- Mass changes mostly occur through surface mediated processes
 - Adsorption/Desorption
 - Particle contamination/wear

Consider low surface area

Higher density, lower roughness

- Shape: Surface area is minimized for spheres, and when h=d for cylinders, centre of mass is easy to determine
- Is the residual magnetic field at the balance pan significant?
 Consider material magnetic susceptibility requirements
- At low residual field: Can use stainless steel or platinum iridium
- At higher fields: low susceptibility materials should be used: copper, tungsten (+low SA, +hard), silicon (-high SA)

Step 1) Magnetic properties

The magnetic force is dependent on the KB residual field profile, the mass shape, and its magnetic susceptibility.

For NRC, the mass pan can be positioned so as to minimize these corrections

The residual field at the mass pan should be known

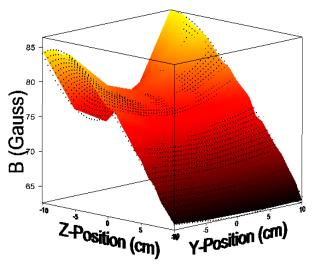
$$F_z = \frac{\chi}{\mu_o} B_o^2 \pi \left[\left(1 + f_1 h + f_2 h^2 \right)^2 - 1 \right] \frac{1}{6g_2} \left[\left(1 + g_2 r^2 \right)^3 - 1 \right]$$

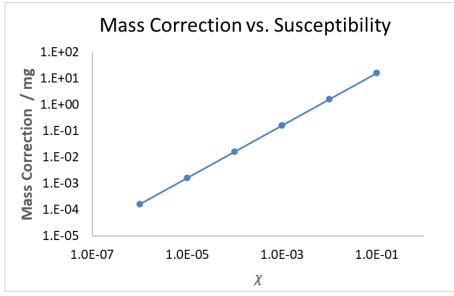
Or approximately

$$F_{z} = \frac{\chi}{2\mu_{o}} \pi r^{2} \left[B^{2}(z=h) - B^{2}(0) \right]$$

h=d=52 mm







Step 1) Vacuum Balance

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- 1 kg Mass comparator
- 0.1 µg resolution
- Typical comparison weighing uncertainty is 3 µg or less (1 kg)

- Operation at constant pressure from 10⁻⁶ mBar to 1000 mBar
- Used for transferring mass value between vacuum and air



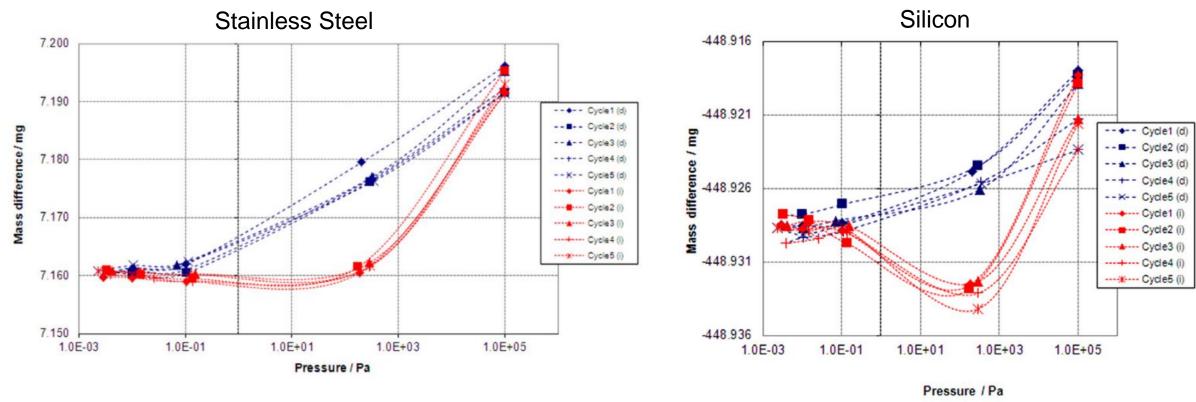
Mettler Toledo Mone



Sartorius CCL1007

Step 1) Mass in Vacuum: Pressure dependence | CCM



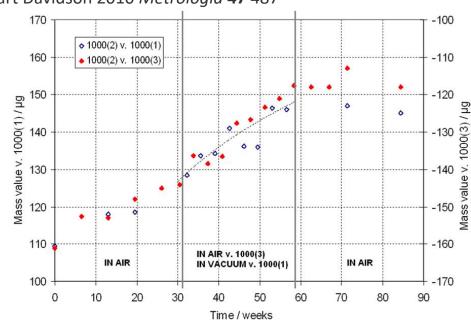


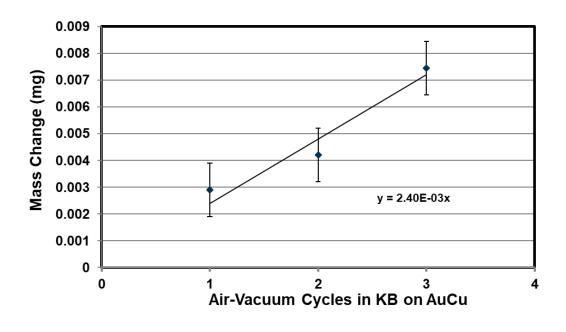
Sorption is typically repeatable between atmospheric pressure and less than 0.1 Pa. Within the same vacuum environments.

Step 1) Mass cycling (Vacuum-Air-Vacuum)



Stuart Davidson 2010 Metrologia 47 487

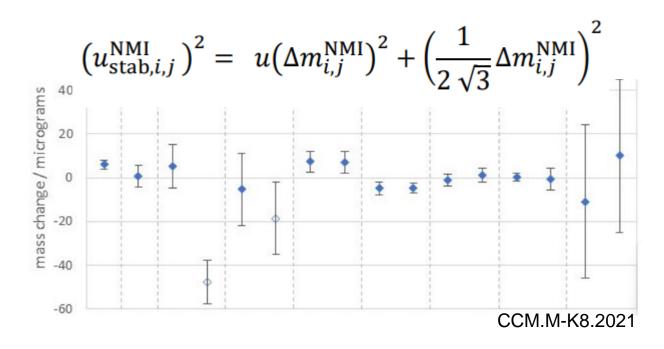




- Cycling in different environments can sometimes cause mass changes
- Typical maximum changes ~2-3 ug per cycle
- Compare to stable masses stored in vacuum before and after realization to track any changes

Step 2) Transport (Vacuum-Air-Vacuum)x2







Travel stability less than 2 µg regularly achieved.







Step 3) Vacuum to Air Transfer Sorption Artefacts † CCM



Disks	Integral
Surface area	125 cm ²
Ratio	1
Water Res.	0

10 Stack		
563 cm ²		
4.5:1		
0.01 ML		

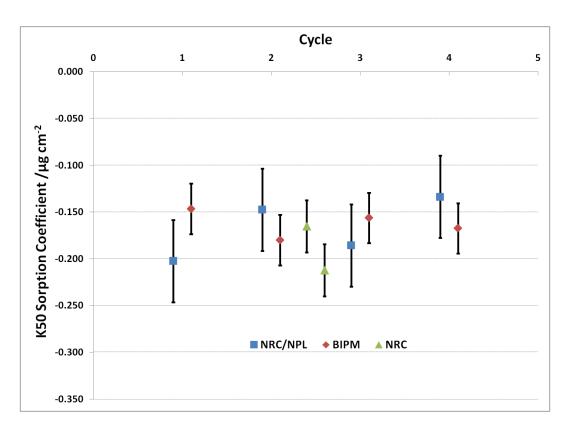
20 Stack	
1262 cm ²	
10:1	
0.0003 ML	

1 ML~ 0.3 ug/cm²

- •Measure the mass difference of the pair in air and vacuum
- •The sensitivity increases with ΔSA ,

Step 3) Surface equivalency





$$s = \frac{\Delta m_{\text{vac}} - \Delta m_{\text{air}}}{A_{\text{stk}} - A_{\text{int}}}$$

Sorption on PtIr artefact as determined by 3 sets of sorption artefacts over several years and laboratories

Step 3) Sorption Values



Author(s)	Material	Surface roughness $(Rz)^b$ (nm)	Sorption Value (μg cm ⁻²)	Pressure (P)a	Time between cleaning and measurement
Schwartz [12]	Stainless steel	120	-0.030^{a}	0.1	<8 months
Schwartz [12]	Stainless steel (uncleaned)	120	-0.076^{a}	0.1	
Picard and Fang [13]	PtIr	10-100	-0.080	0.1	<1 month
Picard and Fang [13]	Silicon	<10	-0.030	0.1	<1 month
Picard and Fang [13]	Stainless steel	10	-0.040	0.1	<1 month
Davidson [14]	PtIr	10	-0.162	10^{-4}	<6 months
Davidson [14]	Stainless steel	60	-0.154	10^{-4}	<6 months
Berry et al [15]	Stainless steel	60	-0.13 to -0.25	$0.05 - 10^{-4}$	<3 years
Mizushima et al [16]	PtIr	5–25	-0.013	$0.1 - 10^{-3}$	<1 year
Berry and Davidson [17]	PtIr	10	-0.070	$0.1 - 10^{-3}$	<5 years
Berry and Davidson [17]	Silicon	<10	-0.050	$0.1 - 10^{-3}$	<5 years
Sanchez et al [5]	PtIr	10-100	-0.162	$0.1 - 10^{-3}$	>20 years

^aCorrected to 50% RH using equations (1) and (2) in [18].

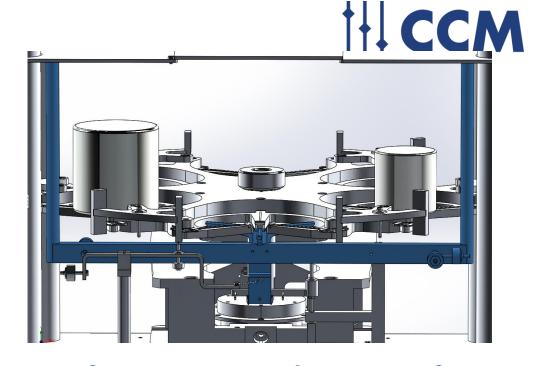
Metrologia **53 (2016) A95**

- Sorption values depend on surface area, cleanliness, roughness, surgace and environmental chemistry
- Without measurement, 1 kg PtIr cylinder can be assumed to have a sorption correction of approximately 8 μ g +/- 7 μ g to span the range of reported values.

^bSurface roughness values are indicative and may have been converted to Rz from Ra or RMS values.

Step3) Dissemination to Air

$$M_t \approx d + \rho_a \Delta V_{t-r} + M_r (1 + (\Delta g_{t-r}/g))$$



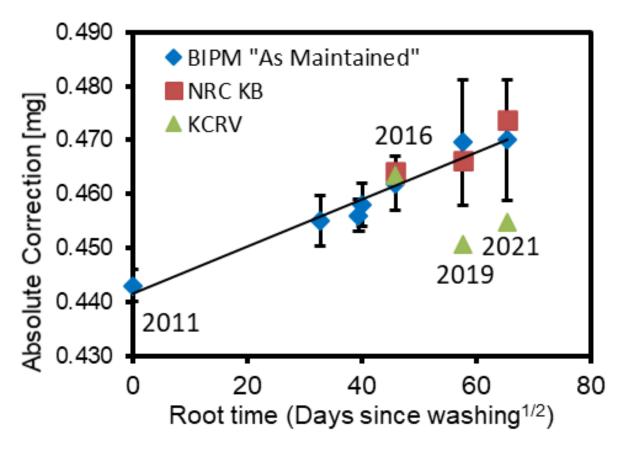
- Once in a vacuum comparator, sorption artefacts can used to transfer the realized value to any type of mass in air:
- Compare the realized mass to sorption artefacts in vacuum, then the same sorption artefact to a stored mass in air

A large buoyancy correction can be replaced by a small sorption correction

Eg. PtIr-SS Buoyancy correction is 98 mg u 9 .8 ug 3 12 ug u=2 ug

Canadian National Standard since 2011





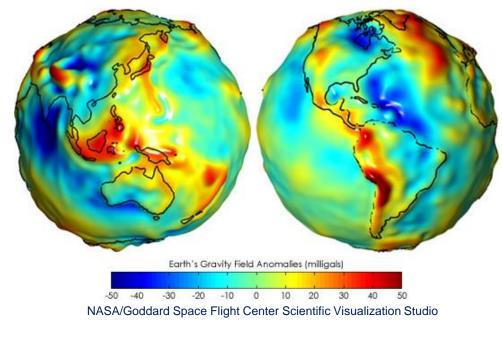
Predictable physical drift, can be used to store the realized value Can be disseminated through traditional mass methods

Gravity



Kibble Equation

$$mg = \frac{IV_c}{v}$$



$$g = G \frac{M_{\oplus}}{r^2}$$

Universal Gravity

$$F = G \frac{m_1 m_2}{r^2}$$

$$g = G rac{M_{\oplus}}{r^2} = 6.67 imes 10^{-11} \; \mathrm{m^3 \cdot kg^{-1} \cdot s^{-2}} imes rac{5.98 imes 10^{24} \; \mathrm{kg}}{(6.38 imes 10^6 \; \mathrm{m})^2} pprox 9.8 \; \mathrm{m \cdot s^{-2}}$$

- Gravitation is a fundamental interaction, which for our purposes (Newtonian) scales the force of attraction between massive bodies.
- Earths gravity varies globally ~100 mGal

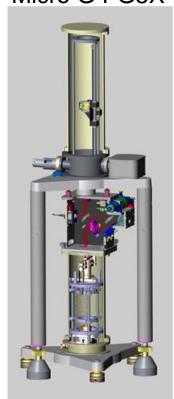
Absolute Gravimeters

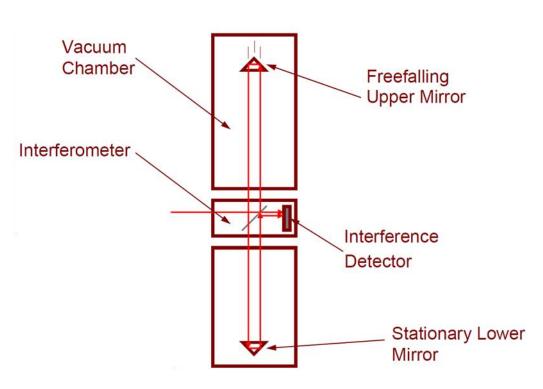
Accuracy <5 ppb,



Accuracy <5 ppb,

Micro G FG5X





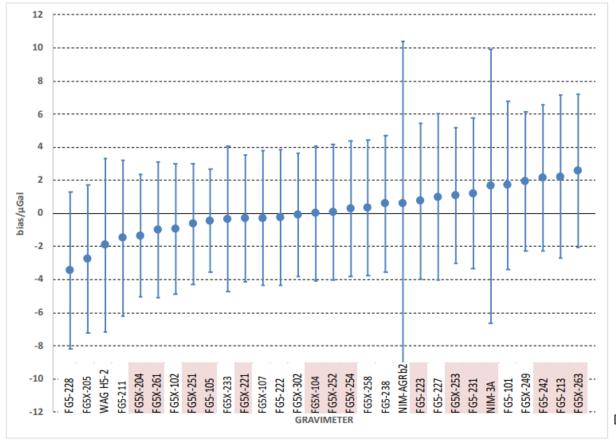


Optical Interferometry of a dropped retroreflector. Not for continuous long term monitoring

Based on atom interferometry Higher sampling rate, no moving parts, long term monitoring

Comparison of absolute gravimeters





David Newell et al 2024 Metrologia 61 07009

CCM.G-K2.2023: Good agreement across all absolute gravimeters All within $^++/-4~\mu Gal$

Relative Gravimeters: Change in g

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Measure change in g



Super conducting gravimeter
Sensitive and Stable, used for long
term change monitoring

Scintrex CG6



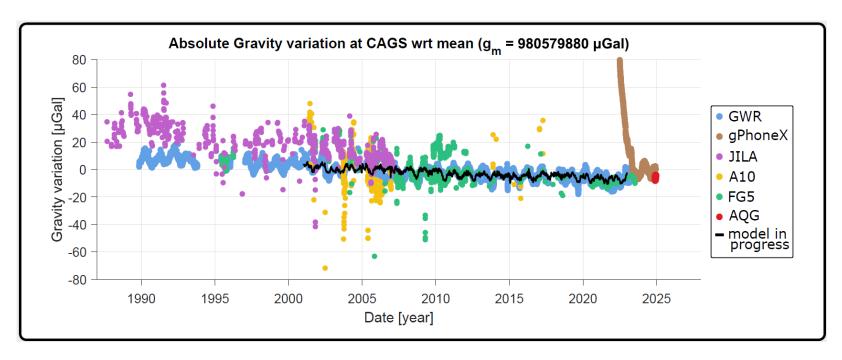
Small and portable Not for long term monitoring gPhoneX



<5 µGal, long term measurement</p>

Canadian Absolute Gravity Station (CAGS)



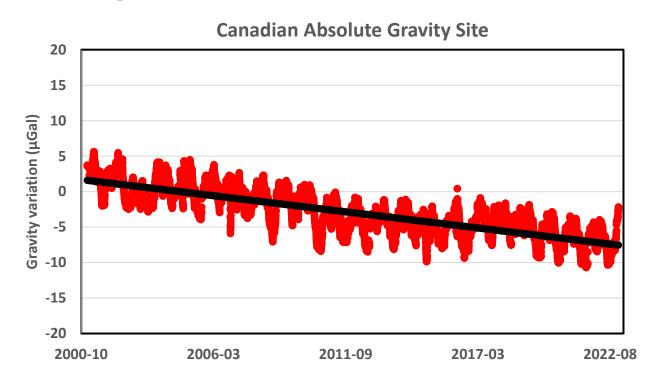


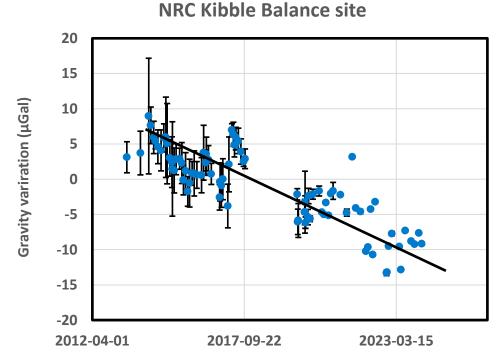
Station Coordinates (Scaled)					
Latitude	Longitude	Elevation	Description		
N45° 35' 7" ± 20.0 m	W75° 48' 27" ± 20.0 m	269.20 ± 1.00 m	CAGS SITE A - CANTLEY		

Gravimetric Information				
Gravity	HI	Gradient		
980579.9292 mGal	0.91 m	0.3770 mGal/m		

Long term and seasonal variation





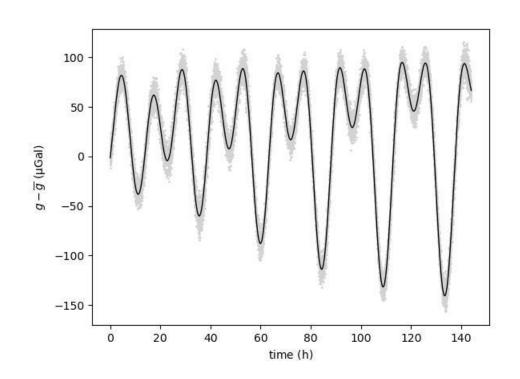


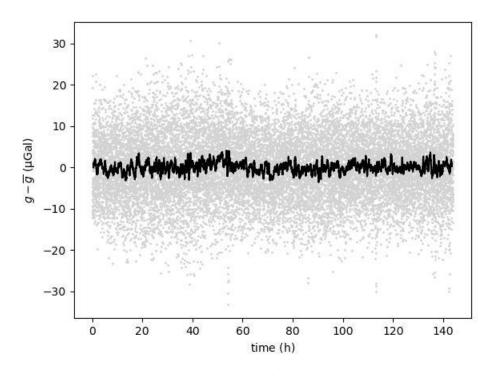
Glacial Rebound ~-0.5 μGal/yr Max deviation: 6 μGal

Glacial Rebound ~-1.3 μGal/yr Max deviation: 7.8 μGal stdev =2.4 μGal FG5 data only

Daily Variation from FG5







6 days of measurement data, peak to peak variation of about 250 ppb Combination of models can be used to extract tides to better than 1 μ Gal

Eg. Tamura (1987). See https://eterna.bkg.bund.de/

Daily Variation



Tidal Models (Impact of celestial bodies)

- Earth Tides: Movement of the earth (largest contributor)
- Ocean loading: Movement of ocean water

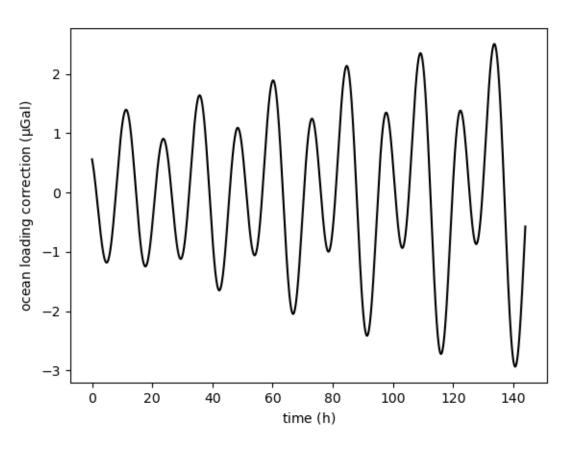
Polar motions: Due to movement of poles (earth axis of rotation)

Pressure: Gravity associated with air column 0.3 μGal/mBar

Can be included into KB servo system to predict required coil current

Daily Variation: Ocean Loading

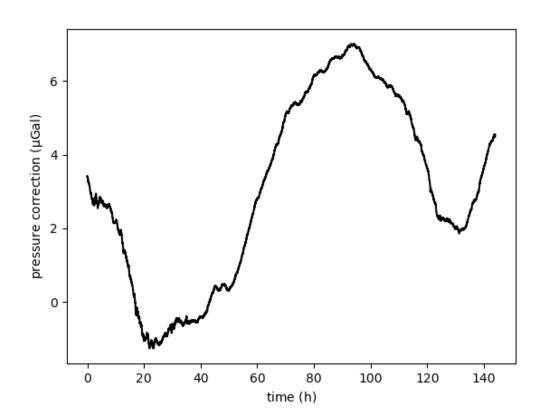


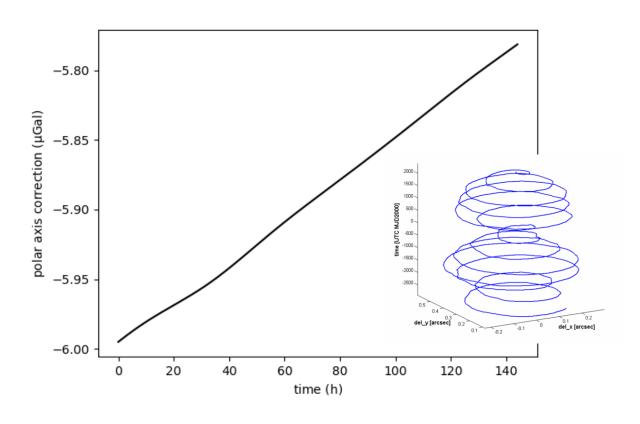


Usually small contribution of a few ppb

Pressure and Polar Motion







Pressure correction from gravitation attraction of air column 0.3 µGal/mBar

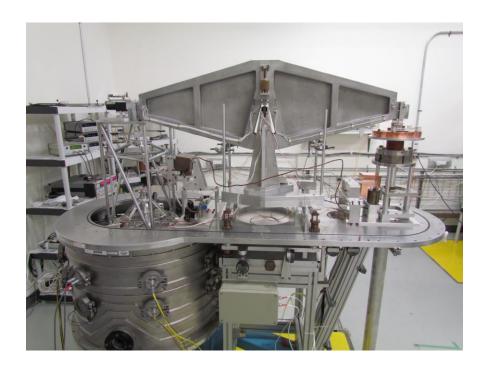
Correction due to polar motion (wobble of earth axis), from IERS

https://www.iers.org/IERS/EN/DataProducts/EarthOrientationData/eop

Gravity Transfer



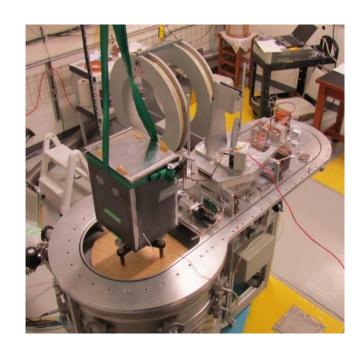




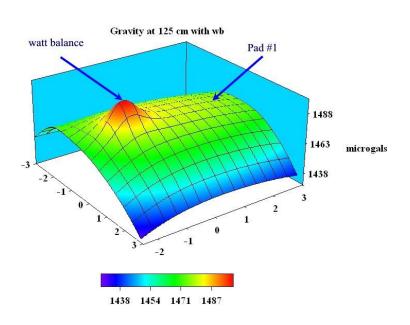
How to transfer absolute g measurement (h~130 cm) to the centre of mass of your artefact for realization?

Relative gravimeter measurements





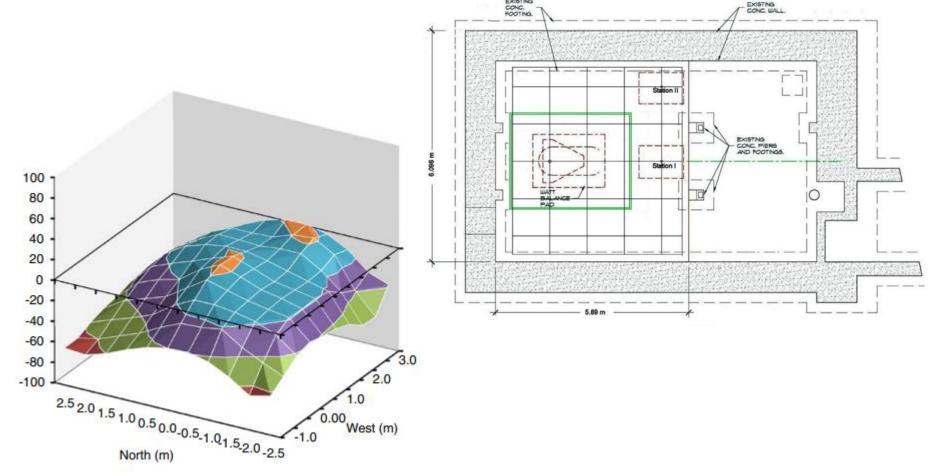
Method 1: Use a relative gravimeter (eg. CG6) to measure the difference between abs g point and Mass artefact position



Method 2: Measure what you can't

Measure Horizontal and Vertical Gradients



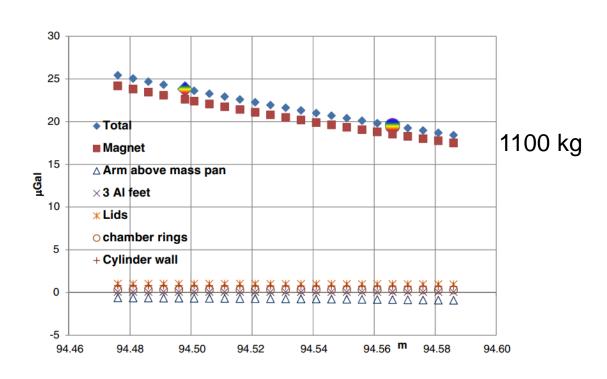




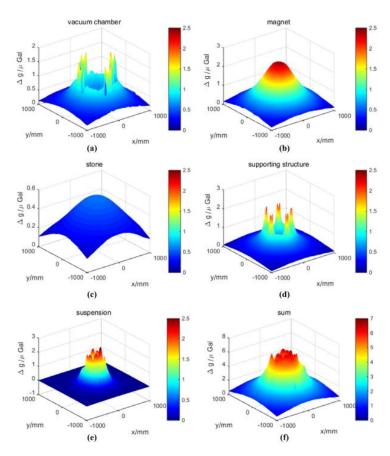
Metrologia 54 (2017) 445

Gravity Modeling of Self attraction





Nagy D 1966 Geophysics 31 362-71 Shisong Li et al 2017 Metrologia 54 445



Metrologia 54 (2017) 445

Summary

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1. Mass:

a. Process for disseminating mass from the Kibble Balance

3 (2) Steps to disseminate realized values

b. Transfer mass selection

Consider mass properties to optimize performance in KB environment

c. Considerations for vacuum to vacuum transfer

Pressure minimum, cycling stability, transport

d. Vacuum to air transfer

Sorption artefacts to account for water/hydrocarbon ad/desorption

2. Gravity:

a. Absolute and Relative Gravimetry

Instruments and seasonal variations

b. Tide Models

Daily changes in gravity due to earth tides, ocean loading, polar motions

c. Gravity Transfer

Methods for transferring g from measurement position of gravimeter to KB mass pan

